

Pointer Analysis: Details

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Outline

- Pointer Statements **Next Topic**
- Comparing Points-to and Alias information
- Defining Points-to Analysis
- Flow Insensitive Points-to Analysis
- Flow Sensitive Points-to Analysis
- Liveness Based Points-to Analysis
- Handling Heap



Pointer Statements

Pointer assignments	Use pointers in expressions
Addr $x = \&y$ Copy $x = y$ Load $x = *y$ $x = y \rightarrow n$ Store $*x = y$ $x \rightarrow n = y$	<i>Use x</i>

- Field accesses such as $x.n$ are treated as new compile time names
- Containment of $x.n$ within x is recorded in terms of offsets
- Heap will be introduced later

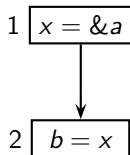


Outline

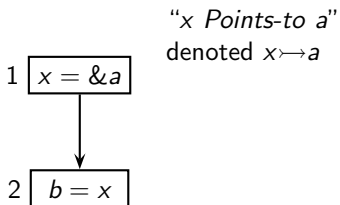
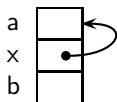
- Pointer Statements
- Comparing Points-to and Alias information **Next Topic**
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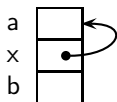
Alias Information Vs. Points-to Information



Alias Information Vs. Points-to Information



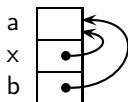
Alias Information Vs. Points-to Information



1 `x = &a`

"*x Points-to a*"
denoted $x \mapsto a$

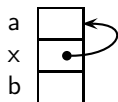
2 `b = x`



"*x and b are Aliases*"
denoted $x \overset{\circ}{=} b$

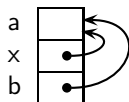


Alias Information Vs. Points-to Information



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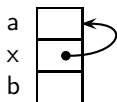
2 $b = x$

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Symmetric
and
Reflexive



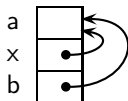
Alias Information Vs. Points-to Information



1 $x = \&a$

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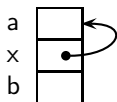
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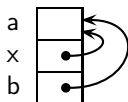
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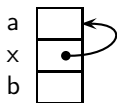
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- What about transitivity?



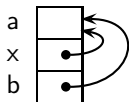
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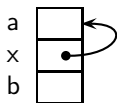
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Symmetric
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- What about transitivity?
 - Points-to: No



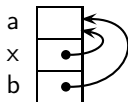
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

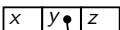
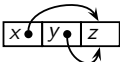
" x and b are Aliases"
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Symmetric
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Reflexive

- What about transitivity?
 - ▶ Points-to: No
 - ▶ Alias: Depends (we will see later)



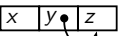
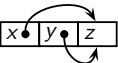


Comparing Points-to and Alias Relations (1)

Statement	Memory	Points-to	Aliases
$x = \&y$	Before (assume) 	Existing	Existing
	After 	New $x \mapsto y$	New Direct $x \overset{\circ}{=} \&y$
$x = y$	Before (assume) 	Existing $y \mapsto z$	Existing $y \overset{\circ}{=} \&z$
	After 	New Direct $x \overset{\circ}{=} y$	New Direct $x \overset{\circ}{=} y$
		New $x \mapsto z$	New Indirect $x \overset{\circ}{=} \&z$





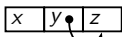
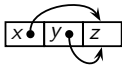
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	After 	New $x \mapsto z$	New Direct $x \overset{\circ}{=} y$
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- Indirect aliases. Substitute a name by its aliases for transitivity



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- Indirect aliases. Substitute a name by its aliases for transitivity
 - Derived aliases. Apply indirection operator to aliases (ignored here)
- $$x \overset{\circ}{=} y \Rightarrow *x \overset{\circ}{=} *y$$

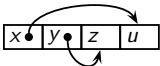


Comparing Points-to and Alias Relations (2)

Statement	Memory	Points-to	Aliases
$*x = y$			
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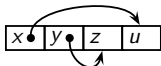
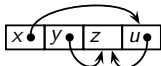


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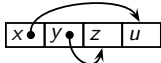



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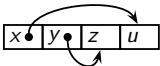
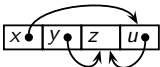



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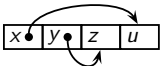
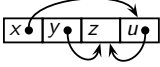
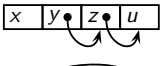
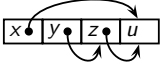


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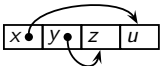
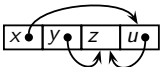
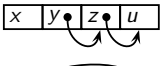
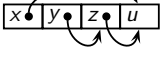


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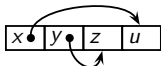
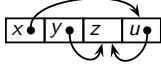
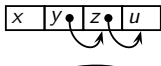
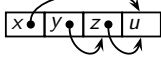


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Comparing Points-to and Alias Relations (2)

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x = *y	<div>Before (assume)</div>  <div>After</div> 	Existing	$y \mapsto z$ $z \mapsto u$	Existing	$y \overset{\circ}{=} \&z$ $z \overset{\circ}{=} \&u$ $*y \overset{\circ}{=} \&u$
				New Direct	$x \overset{\circ}{=} *y$
		New	$x \mapsto u$	New Indirect	$x \overset{\circ}{=} \&u$ $x \overset{\circ}{=} z$
The resulting memories look similar but are different. In the first case we have $u \mapsto z$ whereas in the second case the arrow direction is opposite (i.e. $z \mapsto u$).					



Comparing Points-to and Alias Relations (3)

- Points-to information records edges in the memory graph
- Alias information records paths in the memory graph



Comparing Points-to and Alias Relations (3)

- Points-to information records edges in the memory graph
 - ▶ aliases of the kind $x \doteq \&y$
 x holds the address of y
- Alias information records paths in the memory graph
 - ▶ paths incident on the same node
 x and y hold the same address (and the address is left implicit)



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 - ▶ other aliases can be discovered by composing edges
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More compact but less general

- Alias information records paths in the memory graph
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More general and more complex



An Outline of Pointer Analysis Coverage

- Pointer Statements
- Comparing Points-to and Alias information
- Defining Points-to Analysis **Next Topic**
- Flow Insensitive Points-to Analysis
- Flow Sensitive Points-to Analysis
- Liveness Based Points-to Analysis
- Handling Heap



Concrete States and Traces for Points-to Analysis

Notation	Illustration
V contains all variables	
$P \subseteq V$ contains all pointer variables	
F contains all pointer fields in structures (and also “*”)	
Data states $\sigma : V \times F \rightarrow V$	
Traces τ are sequences of transitions $(n, \sigma) \rightarrow (n', \sigma')$ starting from a given initial n_0, σ_0	



Concrete States and Traces for Points-to Analysis

Notation	Illustration								
V contains all variables	$V = \{a, b, x\}$								
$P \subseteq V$ contains all pointer variables	$P = \{x\}$								
F contains all pointer fields in structures (and also “*”)	$F = \{*, f\}$								
Data states $\sigma : V \times F \rightarrow V$	<table border="1"> <thead> <tr> <th>Program statement</th><th>Corresponding state after each statement</th></tr> </thead> <tbody> <tr> <td>0 : skip</td><td>$\sigma_0 = \emptyset$</td></tr> <tr> <td>1 : $x = \&a$</td><td>$\sigma_1 = \{((x, *) \mapsto a)\}$</td></tr> <tr> <td>2 : $x \rightarrow f = \&b$</td><td>$\sigma_2 = \{((x, *) \mapsto a), ((a, f) \mapsto b)\}$</td></tr> </tbody> </table>	Program statement	Corresponding state after each statement	0 : skip	$\sigma_0 = \emptyset$	1 : $x = \&a$	$\sigma_1 = \{((x, *) \mapsto a)\}$	2 : $x \rightarrow f = \&b$	$\sigma_2 = \{((x, *) \mapsto a), ((a, f) \mapsto b)\}$
Program statement	Corresponding state after each statement								
0 : skip	$\sigma_0 = \emptyset$								
1 : $x = \&a$	$\sigma_1 = \{((x, *) \mapsto a)\}$								
2 : $x \rightarrow f = \&b$	$\sigma_2 = \{((x, *) \mapsto a), ((a, f) \mapsto b)\}$								
Traces τ are sequences of transitions $(n, \sigma) \rightarrow (n', \sigma')$ starting from a given initial n_0, σ_0	Trace $\tau_1 = (0, \sigma_0) \rightarrow (1, \sigma_1) \rightarrow (2, \sigma_2)$								



Ideal Points-to Analysis

For a given statement n

- Reachable States are the states reaching the statement along all traces
- Ideal May-Points-to analysis computes Points-to information reaching along all traces
- Ideal Must-Points-to analysis computes Points-to information that is common to all traces

$$RS(n) = \{\sigma \mid (n, \sigma) \text{ occurs in some trace } \tau\}$$

$$\text{IdealMayPT}(n) = \bigcup_{\sigma \in RS(n)} \sigma$$

$$\text{IdealMustPT}(n) = \bigcap_{\sigma \in RS(n)} \sigma$$



Soundness and Precision of Flow-Sensitive May-Points-to Analysis

A flow-sensitive points-to analysis algorithm A computes $S : N \rightarrow V \times F \times V$

- A flow-sensitive points-to analysis algorithm A is sound if

$$\forall n : S(n) \supseteq \text{IdealMayPT}(n)$$

- A flow-sensitive points-to analysis algorithm A is precise if

$$\forall n : S(n) = \text{IdealMayPT}(n)$$

- A flow-sensitive points-to analysis algorithm A_1 is more precise than A_2 if

$$\forall n : S_2(n) \supseteq S_1(n) \supseteq \text{IdealMayPT}(n)$$

(Precision is meaningful only for a sound analysis)



Soundness and Precision of Flow-Insensitive May-Points-to Analysis

A flow-insensitive points-to analysis algorithm A computes $S : V \times F \times V$

- A flow-insensitive points-to analysis algorithm A is sound if

$$S \supseteq \bigcup_{n \in N} \text{IdealMayPT}(n)$$

- A flow-insensitive points-to analysis algorithm A is precise if

$$S = \bigcup_{n \in N} \text{IdealMayPT}(n)$$

- A flow-insensitive points-to analysis algorithm A_1 is more precise than A_2 if

$$S_2 \supseteq S_1 \supseteq \bigcup_{n \in N} \text{IdealMayPT}(n)$$

(Precision is meaningful only for a sound analysis)



An Outline of Pointer Analysis Coverage

- Pointer Statements
- Comparing Points-to and Alias information
- Defining Points-to Analysis
- Flow Insensitive Points-to Analysis **Next Topic**
- Flow Sensitive Points-to Analysis
- Liveness Based Points-to Analysis
- Handling Heap



Flow Sensitive Vs. Flow Insensitive Pointer Analysis

- Flow insensitive pointer analysis
 - ▶ Inclusion based: Andersen's approach
 - ▶ Equality based: Steensgaard's approach
- Flow sensitive pointer analysis
 - ▶ May points-to analysis
 - ▶ Must points-to analysis



Notation for Andersen's and Steensgaard's Points-to Analysis

- $P_{x.f}$ denotes the set of pointees of pointer variable x along field f
 - ▶ $P_{x.*}$ (concisely written as P_x) denotes the set of pointees of x
 - ▶ If x is a structure, P_x is the set of pointees of all fields of x
- $Unify(x, y)$ unifies locations x and y
 - ▶ x and y are treated as equivalent locations
 - ▶ the pointees of the unified locations are also unified transitively
- $UnifyPTS(x, y)$ unifies the pointees of x and y
 - ▶ x and y themselves are not unified
- We use $x.f$ if the pointees of field f of x are to be unified



Andersen's and Steensgaard's Points-to Analysis

Statement	Andersen's Points-to Sets	Steensgaard's Points-to Sets
$x = \&y$	$P_x \supseteq \{y\}$	$P_x \supseteq \{y\}$ $\forall z \in P_x, \text{Unify}(y, z)$
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For field f of x , we
replace x by $x.f$



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Andersen's view

Steensgaard's view



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Andersen's view

- x points to y
- Include y in the points-to set of x

Steensgaard's view



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Andersen's view

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- Include y in the points-to set of x

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- Equivalence between: All pointees of x
- Unify y and pointees of x



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Andersen's view

- x points to pointees of y
- Include the pointees of y in the points-to set of x

Steensgaard's view



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Andersen's view

- x points to pointees of y
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Steensgaard's view

- Equivalence between: Pointees of x and pointees of y
- Unify points-to sets of x and y



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Andersen's view

- x points to pointees of pointees of y
- Include the pointees of pointees of y in the points-to set of x

Steensgaard's view



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Andersen's view

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Steensgaard's view

- Equivalence between: Pointees of x and pointees of pointees of y
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Andersen's view

- Pointees of x points to pointees of y
- Include the pointees of y in the points-to set of the pointees of x

Steensgaard's view



Andersen's and Steensgaard's Points-to Analysis

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Andersen's view

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Steensgaard's view

- Equivalence between: Pointees of pointees of x and pointees of y
- Unify points-to sets of pointees of x and y



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Inclusion



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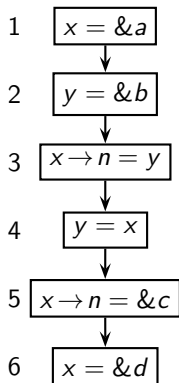
Inclusion

Equality



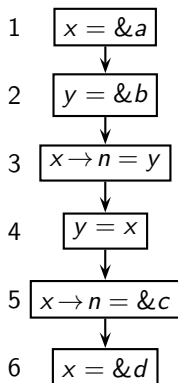
Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program

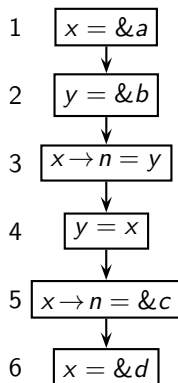


Node	Constraint
1	$P_x \supseteq \{a\}$
2	$P_y \supseteq \{b\}$
3	$\forall z \in P_x, P_{z.n} \supseteq P_y$
4	$P_y \supseteq P_x$
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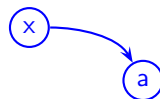
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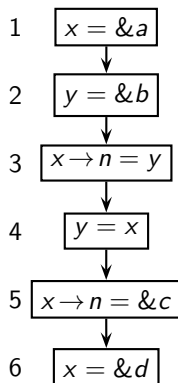
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Points-to Graph



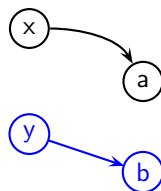
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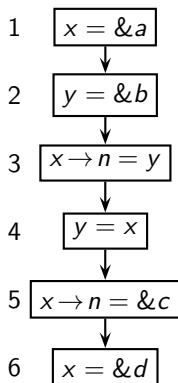
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Points-to Graph



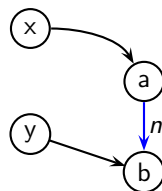
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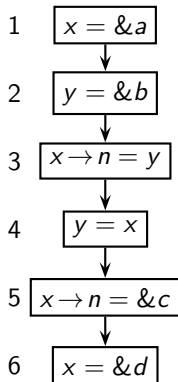
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Points-to Graph



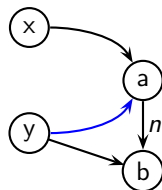
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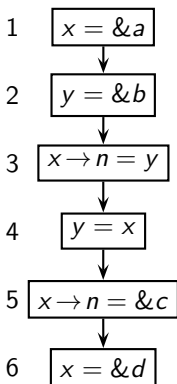
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Points-to Graph



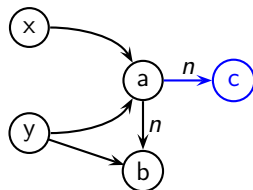
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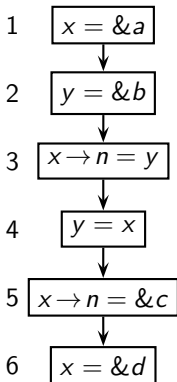
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Points-to Graph



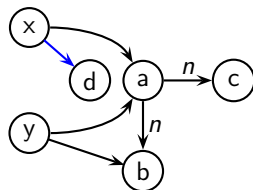
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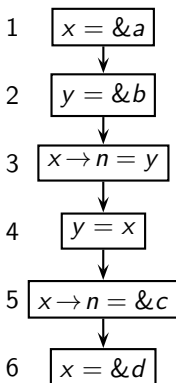
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Points-to Graph



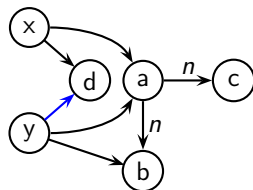
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Points-to Graph

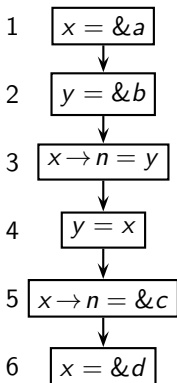


- Since P_x has changed, P_y needs to be processed again
- Order of processing the sets influences efficiency significantly
- A plethora of heuristics have been proposed



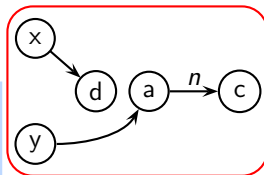
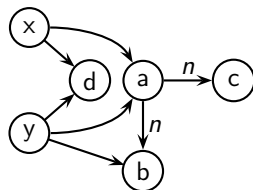
Example of Inclusion Based (aka Andersen's) Points-to Analysis

Program



Node	Constraint
1	$P_x \supseteq \{a\}$
2	$P_y \supseteq \{b\}$
3	$\forall z \in P_x, P_{z.n} \supseteq P_y$
4	$P_y \supseteq P_x$
5	$\forall z \in P_x, P_{z.n} \supseteq \{c\}$
6	$P_x \supseteq \{d\}$

Points-to Graph

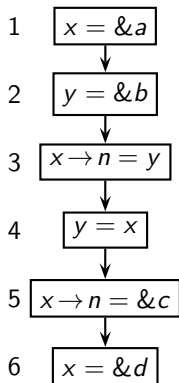


- Actual graph after statement 6 is much simpler with many edges killed
- y does not point to d any time in the execution

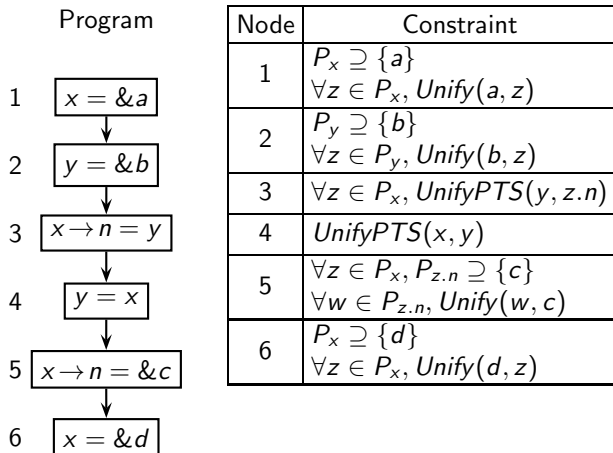


Example of Equality Based (aka Steensgaard's) Points-to Analysis

Program

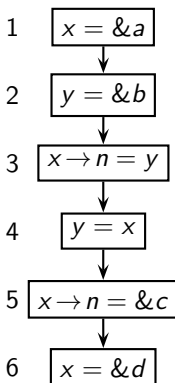


Example of Equality Based (aka Steensgaard's) Points-to Analysis



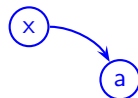
Example of Equality Based (aka Steensgaard's) Points-to Analysis

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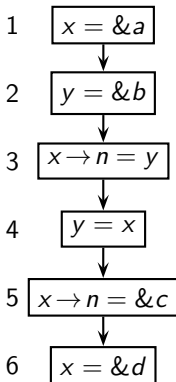
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Points-to Graph



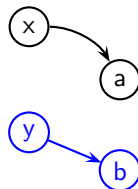
Example of Equality Based (aka Steensgaard's) Points-to Analysis

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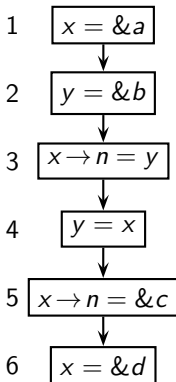
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Points-to Graph



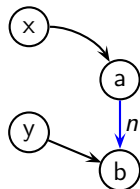
Example of Equality Based (aka Steensgaard's) Points-to Analysis

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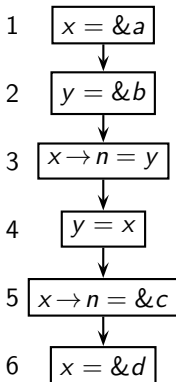
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Points-to Graph



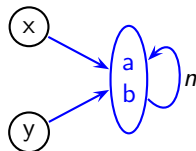
Example of Equality Based (aka Steensgaard's) Points-to Analysis

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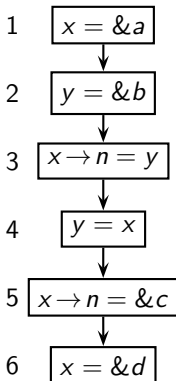
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Points-to Graph



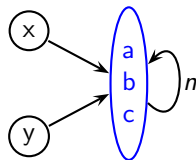
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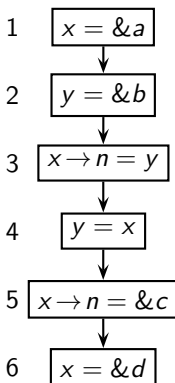
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Points-to Graph



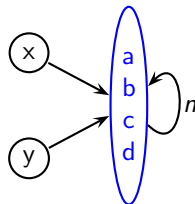
Example of Equality Based (aka Steensgaard's) Points-to Analysis

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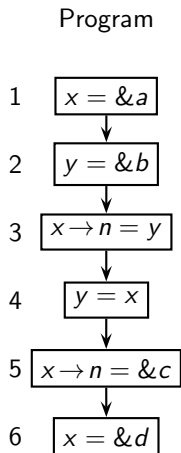


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Points-to Graph

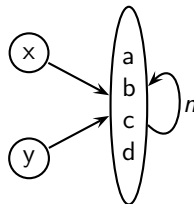


Example of Equality Based (aka Steensgaard's) Points-to Analysis



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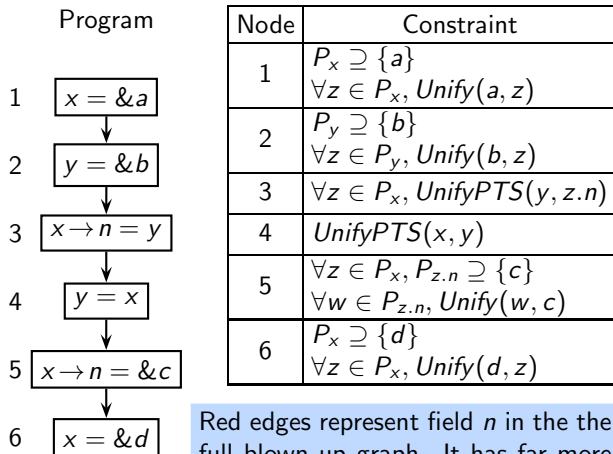
Points-to Graph



No further change



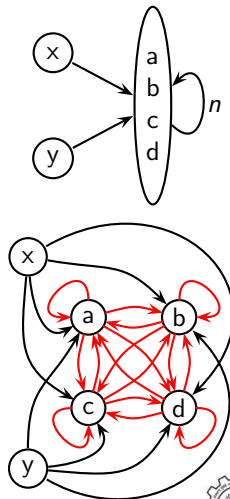
Example of Equality Based (aka Steensgaard's) Points-to Analysis



Red edges represent field n in the the full blown up graph. It has far more edges than in Andersen's graph

Far more efficient but far less precise

Points-to Graph



Comparing Equality and Inclusion Based Analyses

- Andersen's algorithm is cubic in number of pointers
- Steensgaard's algorithm is nearly linear in number of pointers
- How can it be more efficient by an orders of magnitude?
 - ▶ Andersen's inclusion based wisdom:
Add edges and let the number of successors increase
 - ▶ Steensgaard's equality based wisdom:
Merge multiple successors and maintain a single successor of any node



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- Since a larger number of pointers treated are alike and fewer distinctions are maintained, Steensgaard's points-to graphs (with unified nodes) are much smaller
- Efficient *Union-Find* algorithms to merge intersecting subsets

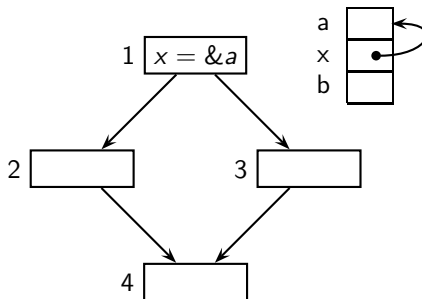


An Outline of Pointer Analysis Coverage

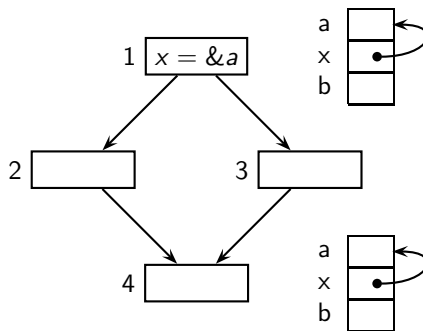
- Pointer Statements
- Comparing Points-to and Alias information
- Defining Points-to Analysis
- Flow Insensitive Points-to Analysis
- Flow Sensitive Points-to Analysis Next Topic
- Liveness Based Points-to Analysis
- Handling Heap



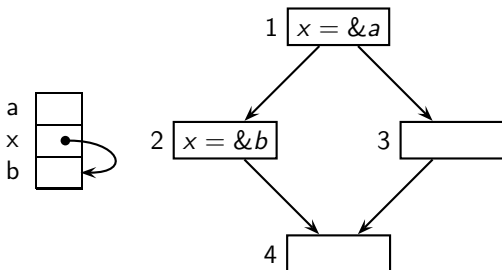
Must Points-to Information



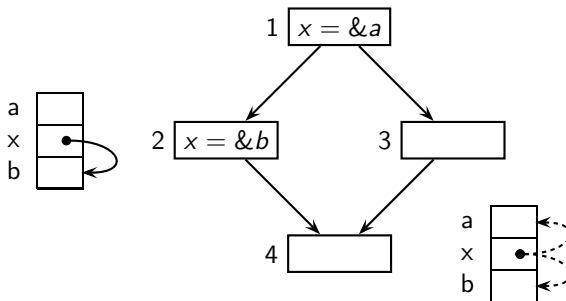
Must Points-to Information



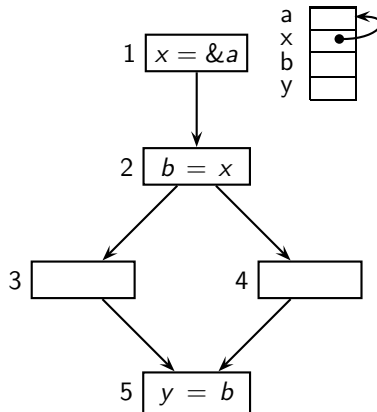
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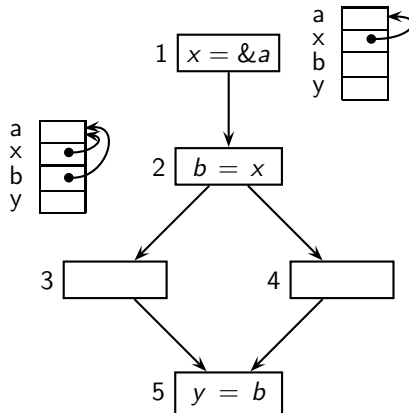
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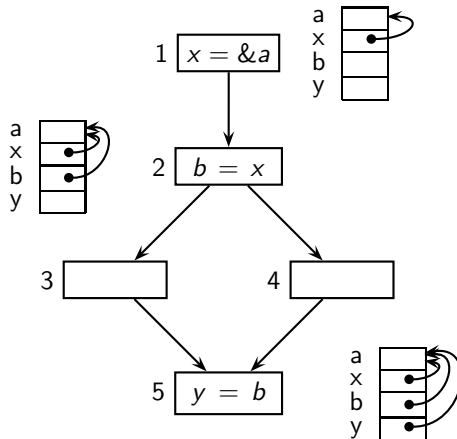
Must Alias Information



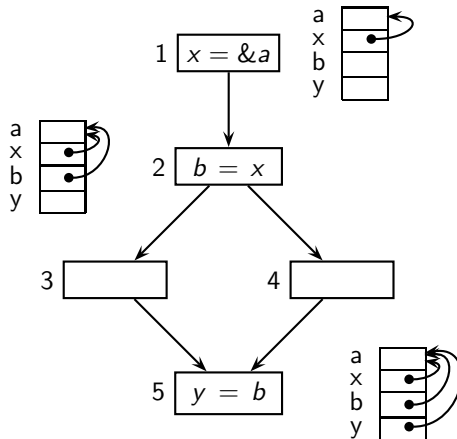
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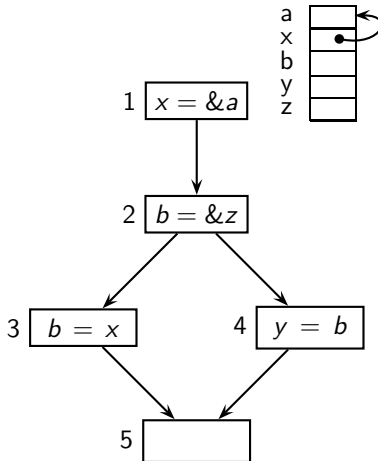
Must Alias Information



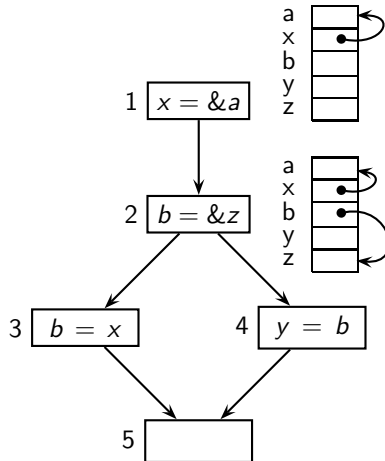
$$x \overset{\circ}{=} b \text{ and } b \overset{\circ}{=} y \Rightarrow x \overset{\circ}{=} y$$



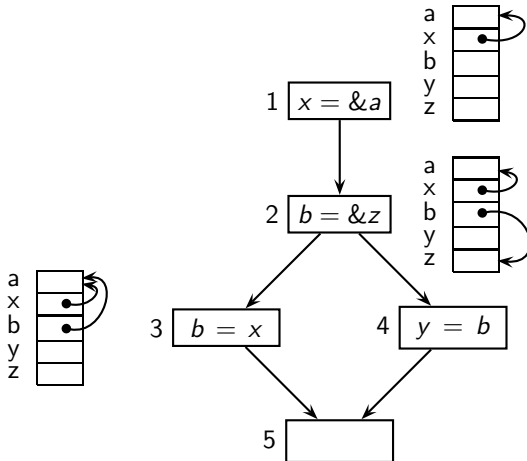
May Alias Information



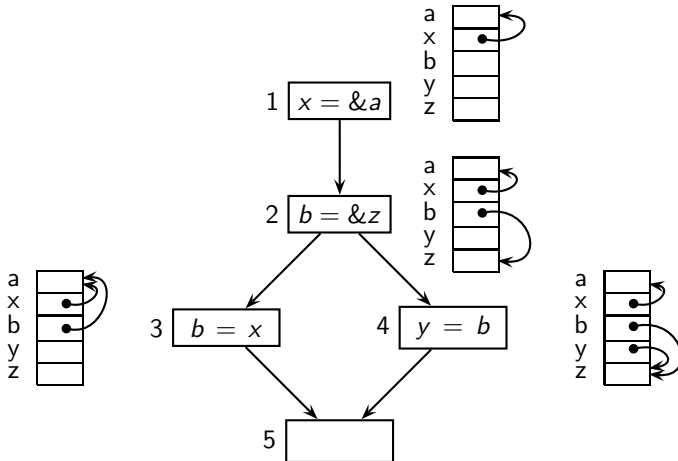
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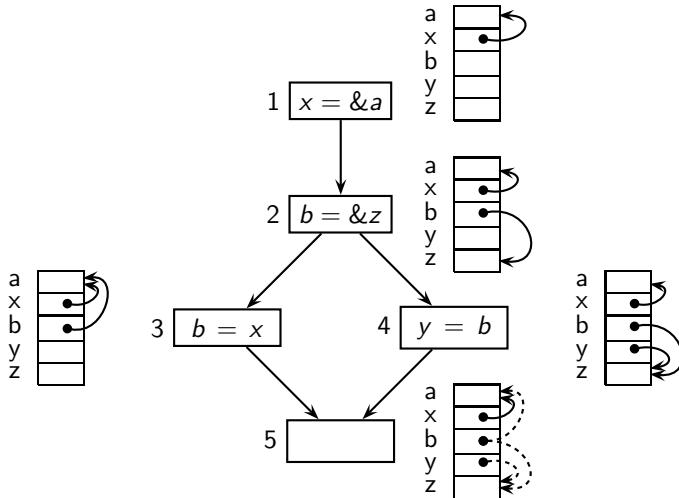
May Alias Information



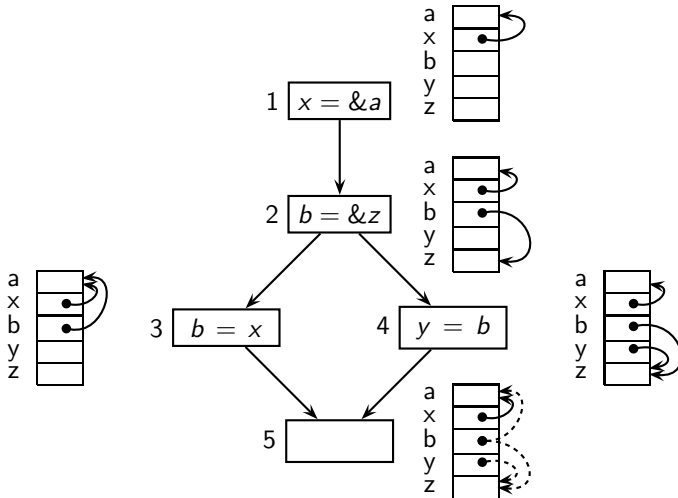
May Alias Information



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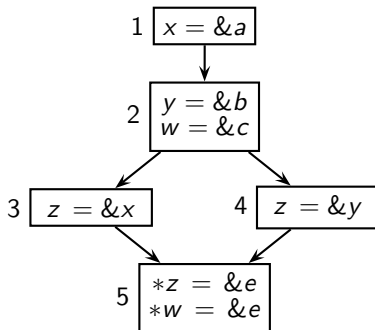
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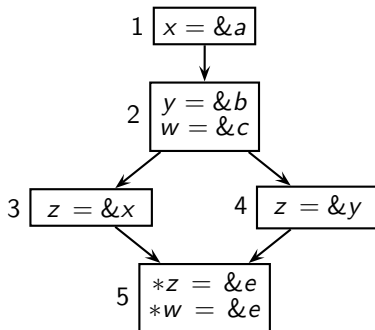
$$x \doteq b \text{ and } b \doteq y \not\Rightarrow x \doteq y$$



Strong and Weak Updates



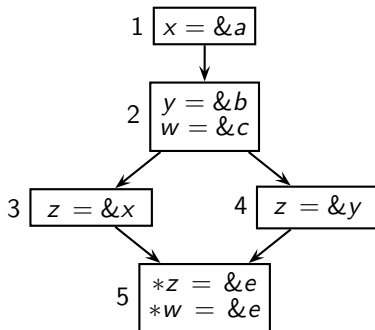
Strong and Weak Updates



Weak update: Modification of x or y due to $*z$ in block 5



Strong and Weak Updates

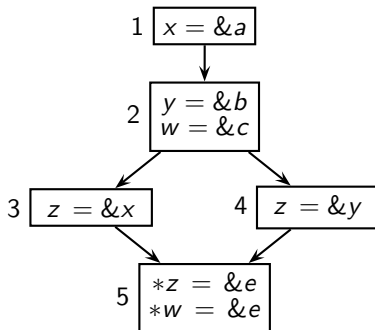


Weak update: Modification of x or y due to $*z$ in block 5

Strong update: Modification of c due to $*w$ in block 5



Strong and Weak Updates



Weak update: Modification of x or y due to $*z$ in block 5

Strong update: Modification of c due to $*w$ in block 5

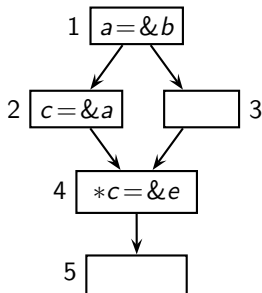
How is this concept related to May/Must nature of information?



May and Must Analysis for Killing Points-to Information (1)

May Points-to Analysis

Must Points-to Analysis

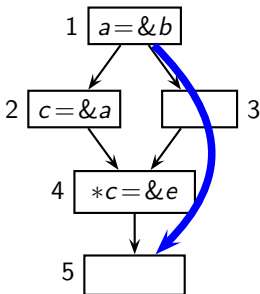


May and Must Analysis for Killing Points-to Information (1)

May Points-to Analysis

- (a, b) should be in $MayIn_5$
Holds along path 1-3-4
- Block 4 should not kill (a, b)
- Possible if pointee set of c is \emptyset
- However, $MayIn_4$ contains (c, a)

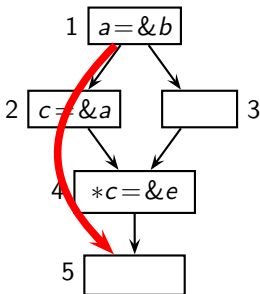
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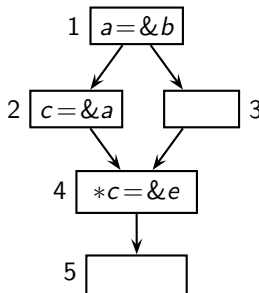
- (a, b) should not be in $MustIn_5$
Does not hold along path 1-2-4
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May and Must Analysis for Killing Points-to Information (1)

May Points-to Analysis

- (a, b) should be in $MayIn_5$
Holds along path 1-3-4
- Block 4 should not kill (a, b)
- Possible if pointee set of c is \emptyset (Use $MustIn_4$)
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Must Points-to Analysis

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Does not hold along path 1-2-4
- Block 4 should kill (a, b)
- Possible if pointee set of c is $\{a\}$ (Use $MayIn_4$)
- However, $MustIn_4$ contains (a, b)

For killing points-to information through indirection,

- **Must** points-to analysis should identify pointees of c using $MayIn_4$
- **May** points-to analysis should identify pointees of c using $MustIn_4$



May and Must Analysis for Killing Points-to Information (2)

- May Points-to analysis should remove a May points-to pair
 - ▶ only if it must be removed along all paths

Kill should remove only strong updates

⇒ should use Must Points-to information

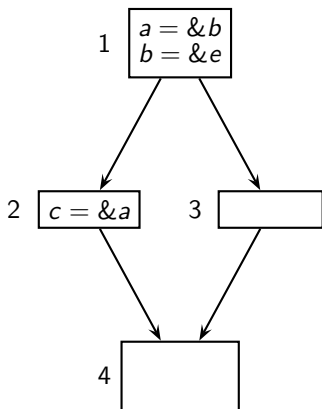
- Must Points-to analysis should remove a Must points-to pair
 - ▶ if it can be removed along any path

Kill should remove all weak updates

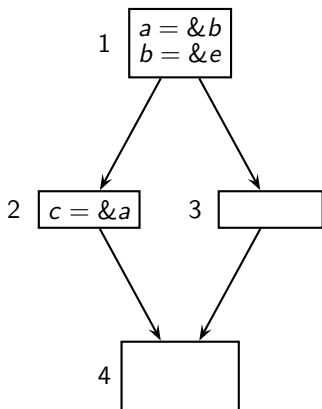
⇒ should use May Points-to information



Discovering Must Points-to Information from May Points-to Information



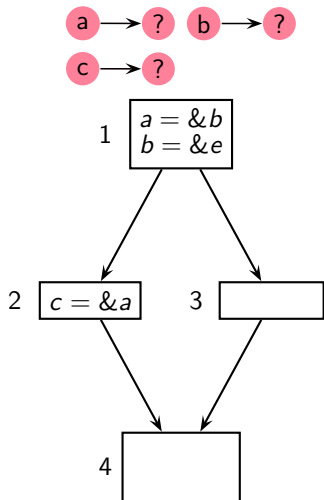
Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”
Assume that e is a scalar



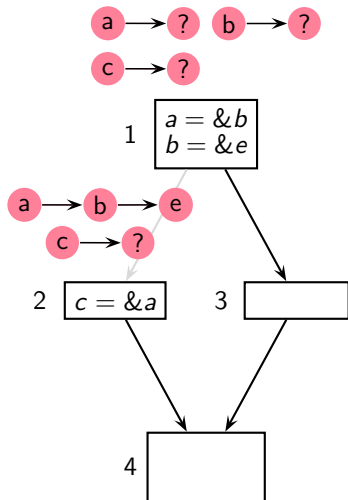
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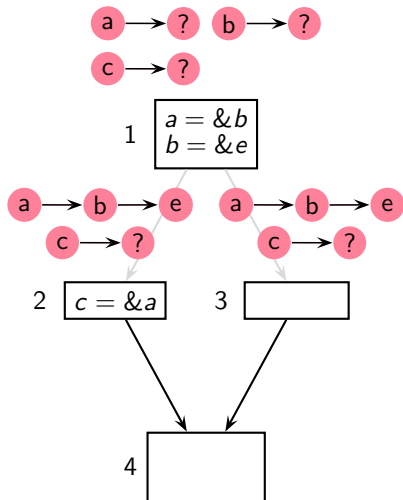
Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to "?"
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- Perform usual may points-to analysis



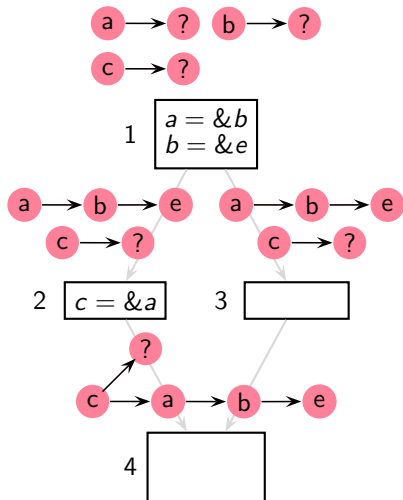
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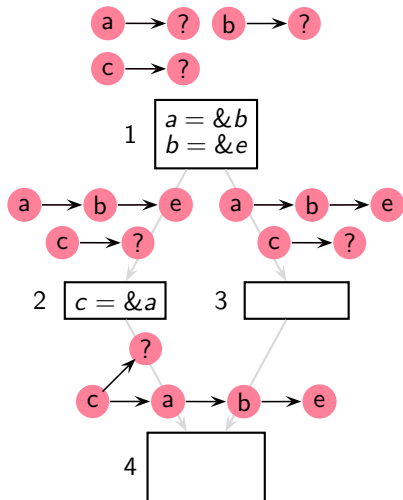
Discovering Must Points-to Information from May Points-to Information



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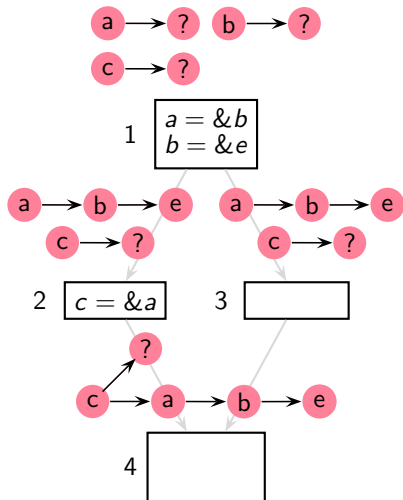
Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”
Assume that e is a scalar
- Perform usual may points-to analysis
- Since c has multiple pointees, it is a MAY relation



Discovering Must Points-to Information from May Points-to Information



- *Bl.* every pointer points to “?”
Assume that e is a scalar
- Perform usual may points-to analysis
- Since c has multiple pointees, it is a MAY relation
- Since a has a single pointee, it is a MUST relation



Relevant Algebraic Operations on Relations (1)

- Let $\mathbf{P} \subseteq V$ be the set of pointer variables
- May-points-to information: $\mathcal{A} = \langle 2^{\mathbf{P} \times V}, \supseteq \rangle$
- Standard algebraic operations on points-to relations

Given relation $R \subseteq \mathbf{P} \times V$ and $X \subseteq \mathbf{P}$,

- ▶ Relation *application* $R X = \{v \mid u \in X \wedge (u, v) \in R\}$
- ▶ Relation *restriction* $(R|_X) R|_X = \{(u, v) \in R \mid u \in X\}$



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- ▶ Relation *application* $R X = \{v \mid u \in X \wedge (u, v) \in R\}$
(Find out the pointees of the pointers contained in X)
- ▶ Relation *restriction* $(R|_X)$ $R|_X = \{(u, v) \in R \mid u \in X\}$
(Restrict the relation only to the pointers contained in X by removing points-to information of other pointers)



Relevant Algebraic Operations on Relations (2)

Let

$$V = \{a, b, c, d, e, f, g, ?\}$$

$$\mathbf{P} = \{a, b, c, d, e\}$$

$$R = \{(a, b), (a, c), (b, d), (c, e), (c, g), (e, ?)\}$$

$$X = \{a, c\}$$

Then,

$$R \ X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$R|_X = \{(u, v) \in R \mid u \in X\}$$



Relevant Algebraic Operations on Relations (2)

Let

$$V = \{a, b, c, d, e, f, g, ?\}$$

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$$X = \{a, c\}$$

Then,

$$R X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$= \{b, c, e, g\}$$

$$R|_X = \{(u, v) \in R \mid u \in X\}$$



Relevant Algebraic Operations on Relations (2)

Let

$$V = \{a, b, c, d, e, f, g, ?\}$$

$$\mathbf{P} = \{a, b, c, d, e\}$$

$$R = \{(a, b), (a, c), (b, d), (c, e), (c, g), (e, ?)\}$$

$$X = \{a, c\}$$

Then,

$$R X = \{v \mid u \in X \wedge (u, v) \in R\}$$

$$= \{b, c, e, g\}$$

$$R|_X = \{(u, v) \in R \mid u \in X\}$$

$$= \{(a, b), (a, c), (c, e), (c, g)\}$$



Points-to Analysis Data Flow Equations

$$Ain_n = \begin{cases} V \times \{?\} & n \text{ is } Start_p \\ \bigcup_{p \in pred(n)} Aout_p & \text{otherwise} \end{cases}$$
$$Aout_n = \left(Ain_n - \left(Kill_n \times V \right) \right) \cup \left(Def_n \times Pointee_n \right)$$

- $Ain/Aout$: sets of mAy points-to pairs
- $Kill_n$, Def_n , and $Pointee_n$ are defined in terms of Ain_n



Points-to Analysis Data Flow Equations

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- $Ain/Aout$: sets of memory points-to pairs
- $Kill_n$, Def_n , and $Pointee_n$ are defined in terms of Ain_n

Pointers whose
points-to relations should
be removed



Points-to Analysis Data Flow Equations

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- $Ain/Aout$: sets of mAy points-to pairs
- $Kill_n$, Def_n , and $Pointee_n$ are defined in terms of Ain_n

Pointers that are defined (i.e. pointers in which addresses are stored)



Points-to Analysis Data Flow Equations

Pointees (i.e. locations whose addresses are stored)

$$Ain_n = \begin{cases} V \times \{?\} & n \text{ is } Start_p \\ \bigcup_{p \in pred(n)} Aout_p & \text{otherwise} \end{cases}$$

$$Aout_n = \left(Ain_n - \left(Kill_n \times V \right) \right) \cup \left(Def_n \times \boxed{Pointee_n} \right)$$

- $Ain/Aout$: sets of mAy points-to pairs
- $Kill_n$, Def_n , and $Pointee_n$ are defined in terms of Ain_n



Points-to Analysis Data Flow Equations

$$\begin{aligned} \text{Ain}_n &= \begin{cases} V \times \{?\} & n \text{ is } \text{Start}_p \\ \bigcup_{p \in \text{pred}(n)} \text{Aout}_p & \text{otherwise} \end{cases} \\ \text{Aout}_n &= \left(\text{Ain}_n - \left(\text{Kill}_n \times V \right) \right) \cup \left(\text{Def}_n \times \text{Pointee}_n \right) \end{aligned}$$

- Ain/Aout : sets of mAy points-to pairs
- Kill_n , Def_n , and Pointee_n are defined in terms of Ain_n



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$			
$x = \&a$			
$x = y$			
$x = *y$			
$*x = y$			
other			



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$			
$x = \&a$			
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Pointers that are defined (i.e. pointers in which addresses are stored)

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other			

Pointees (i.e. locations
whose addresses are
stored)



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$			
$x = \&a$			
$x = y$			
$x = *y$			
$*x = y$			
other			

Pointers whose
points-to relations should
be removed



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$			
$x = y$			
$x = *y$			
$*x = y$			
other			



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$			
$x = *y$			
$*x = y$			
other			



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$			
$*x = y$			
other			

Pointees of y in Ain_n are the targets of defined pointers



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$			
other			

Pointees of those
pointees of y in Ain_n which
are pointers



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

Pointees of
 x in Ain_n receive new
addresses



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n

Strong update using must-points-to information computed from Ain_n

	Def_n	$Kill_n$	
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n

Strong update using
must-points-to information
computed from Ain_n

	Def_n	$Kill_n$	
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$

Find out
must-pointees of
all pointers



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n

Strong update using must-points-to information computed from Ain_n

	Def_n	$Kill_n$	
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} \\ \emptyset \end{cases} \quad \begin{cases} R\{z\} = \{w\} \wedge w \neq ? \\ \text{otherwise} \end{cases}$$

z has a single pointee w in must-points-to relation



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n

Strong update using must-points-to information computed from Ain_n

	Def_n	$Kill_n$	
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$

z has no pointee in must-points-to relation



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other			

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} \\ \emptyset \end{cases} \quad \begin{matrix} R\{z\} = \{w\} \wedge w \neq ? \\ \text{otherwise} \end{matrix}$$

Pointees of y in Ain_n are the targets of defined pointers



Extractor Functions for Points-to Analysis

Values defined in terms of Ain_n (denoted A)

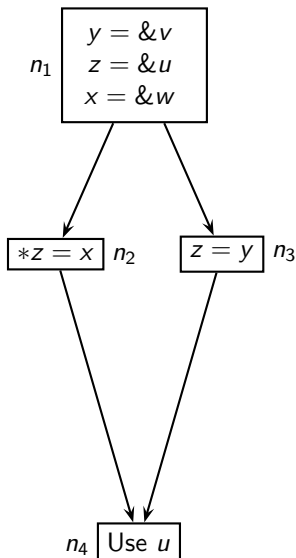
	Def_n	$Kill_n$	$Pointee_n$
$use\ x$	\emptyset	\emptyset	\emptyset
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$
other	\emptyset	\emptyset	\emptyset

$$Must(R) = \bigcup_{z \in \mathbf{P}} \{z\} \times \begin{cases} \{w\} & R\{z\} = \{w\} \wedge w \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers

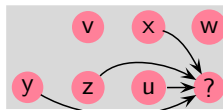


An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers

n_1

```
y = &v
z = &u
x = &w
```



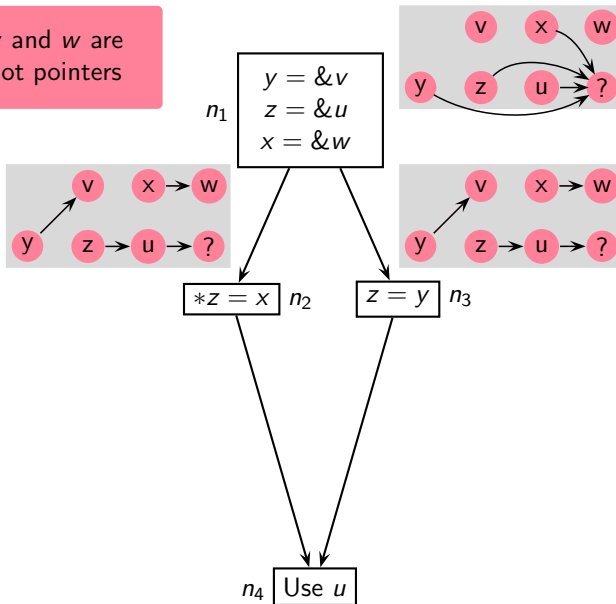
$*z = x$ n_2

$z = y$ n_3

n_4 Use u

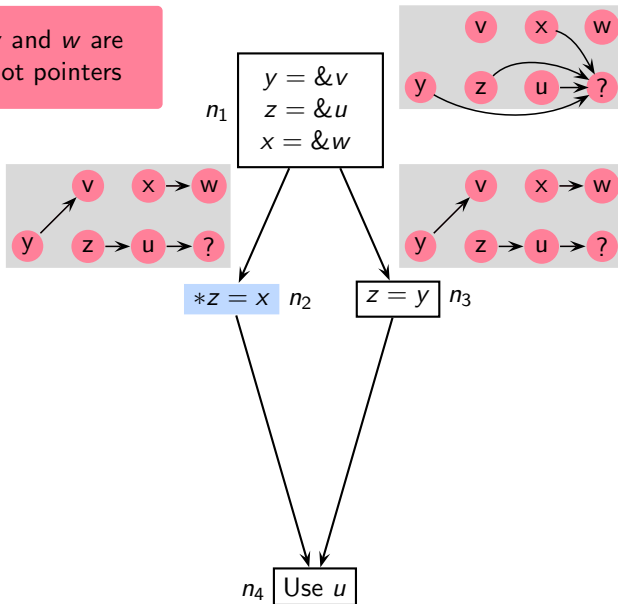
An Example of Flow Sensitive May Points-to Analysis

v and w are
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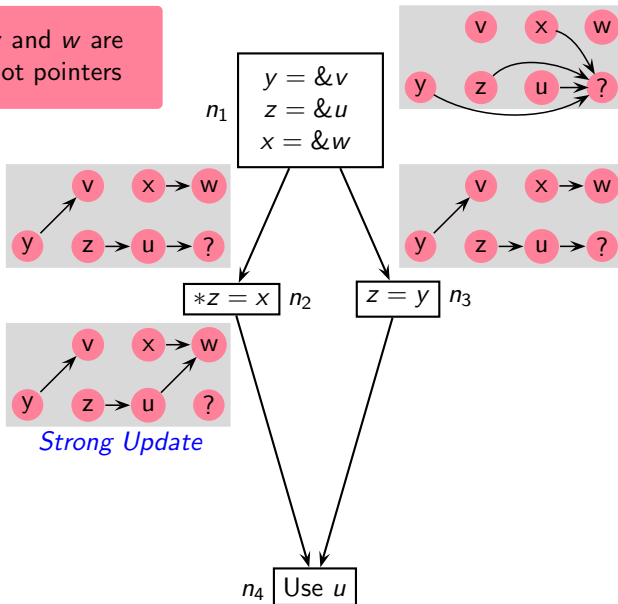
An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers



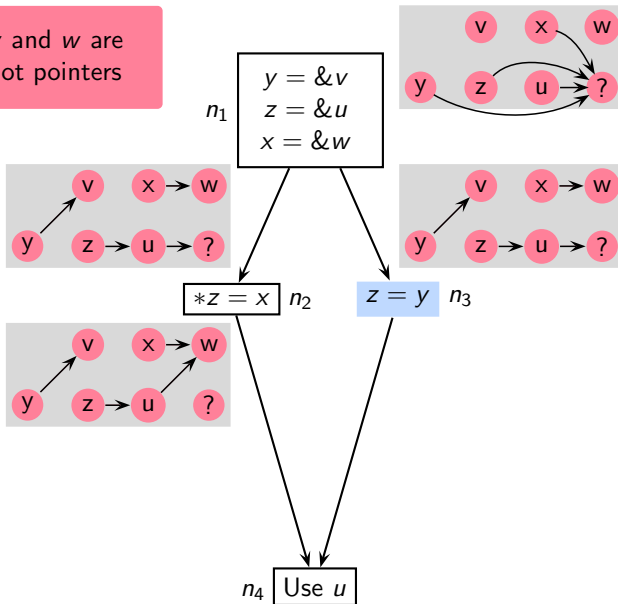
An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers



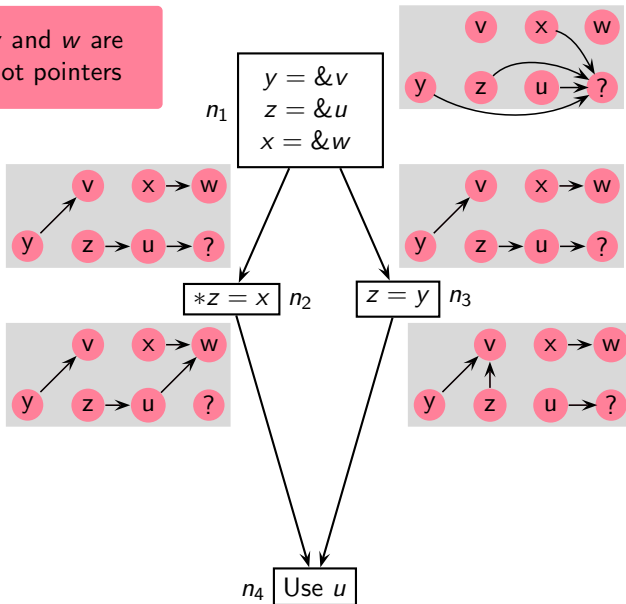
An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers



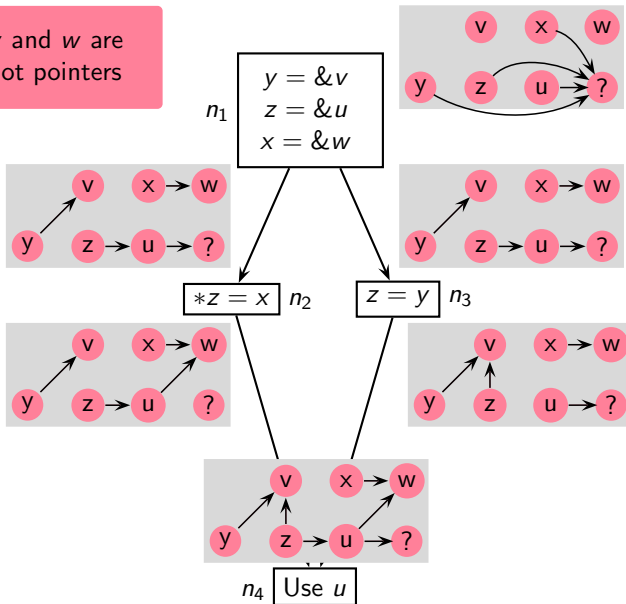
An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers



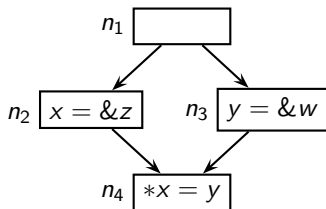
An Example of Flow Sensitive May Points-to Analysis

v and w are
not pointers

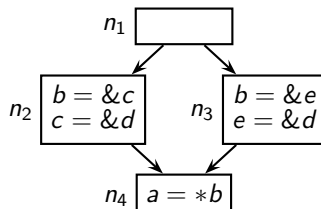


Non-Distributivity of Points-to Analysis

May Points-to

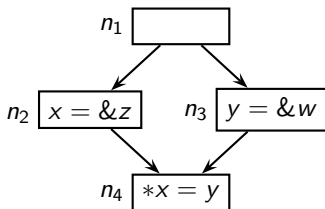


Must Points-to



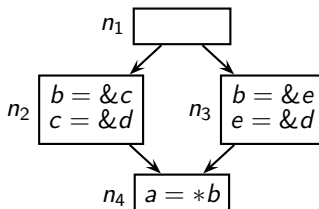
Non-Distributivity of Points-to Analysis

May Points-to



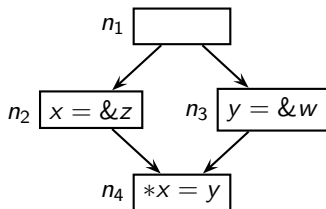
$z \mapsto w$ is spurious

Must Points-to



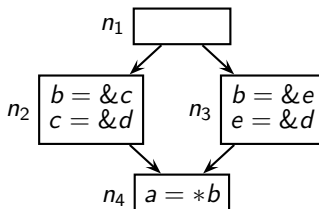
Non-Distributivity of Points-to Analysis

May Points-to



$z \mapsto w$ is spurious

Must Points-to



$a \mapsto d$ is missing

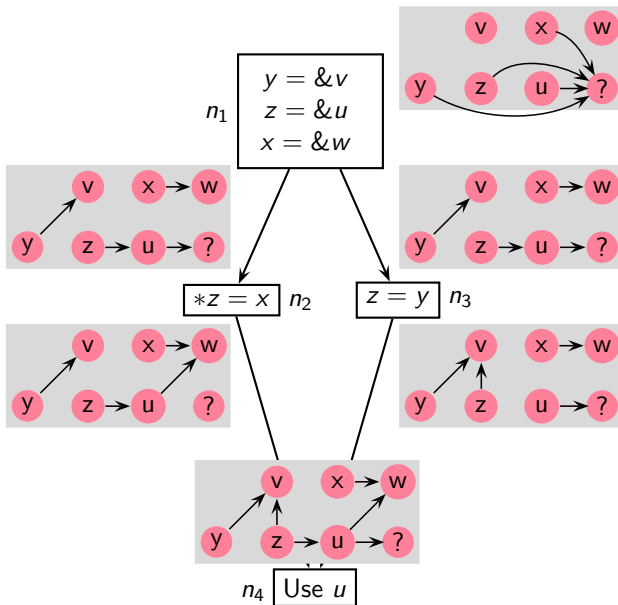


An Outline of Pointer Analysis Coverage

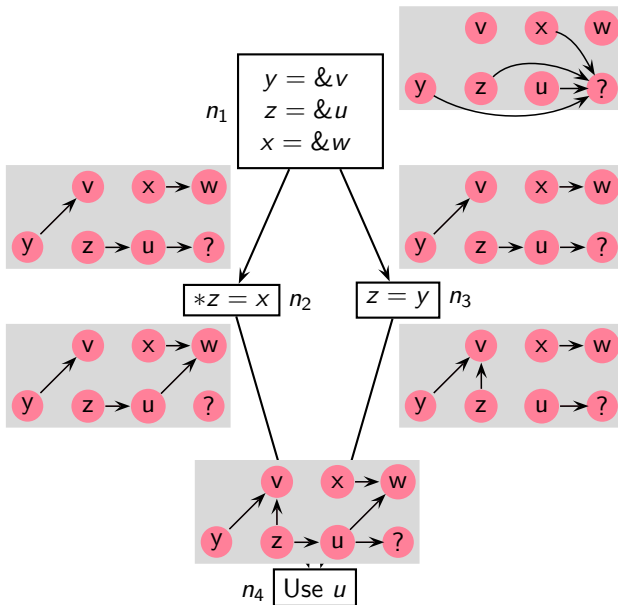
- Pointer Statements
- Comparing Points-to and Alias information
- Defining Points-to Analysis
- Flow Insensitive Points-to Analysis
- Flow Sensitive Points-to Analysis
- Liveness Based Points-to Analysis Next Topic
- Handling Heap



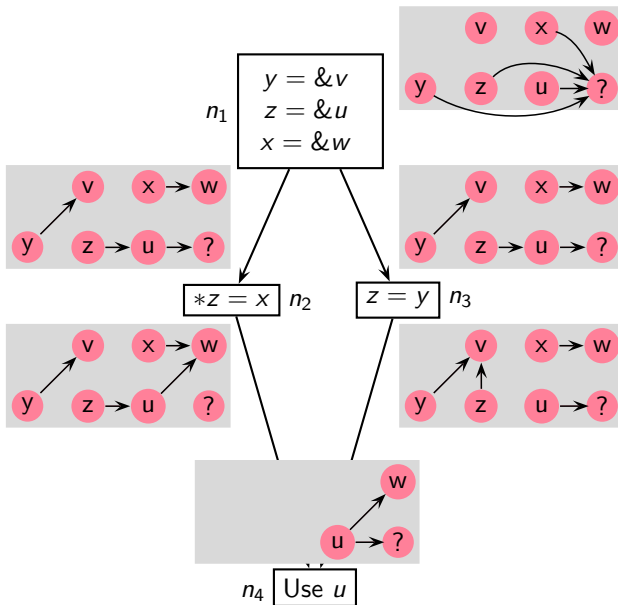
Our Motivating Example for FCPA



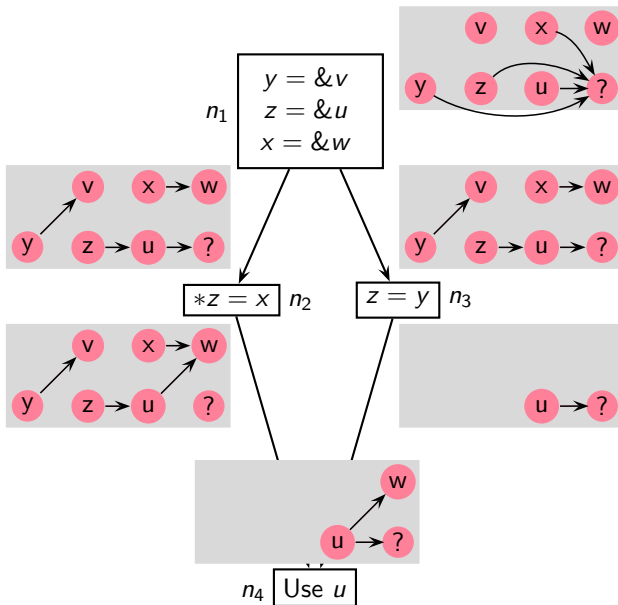
Is All This Information Useful?



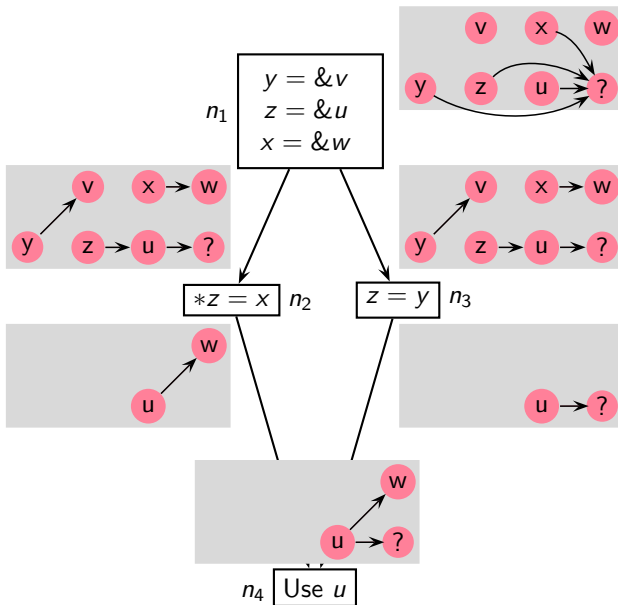
Is All This Information Useful?



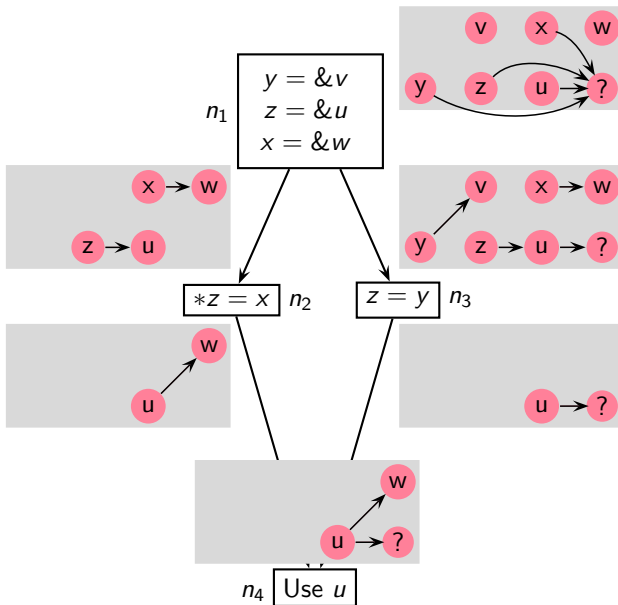
Is All This Information Useful?



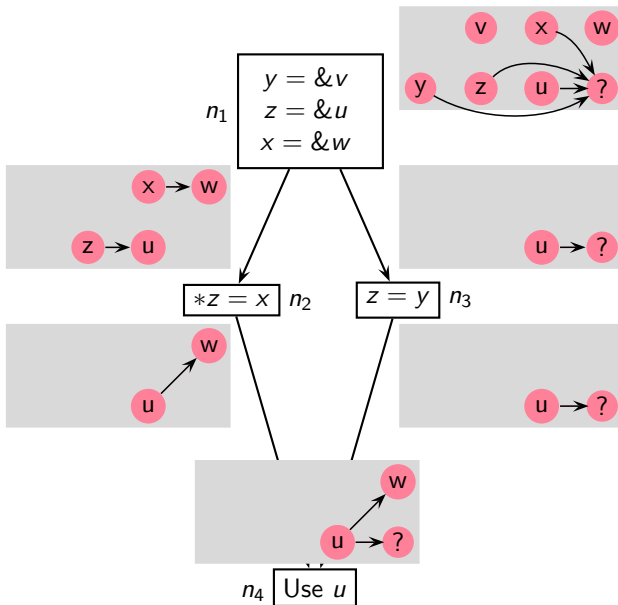
Is All This Information Useful?



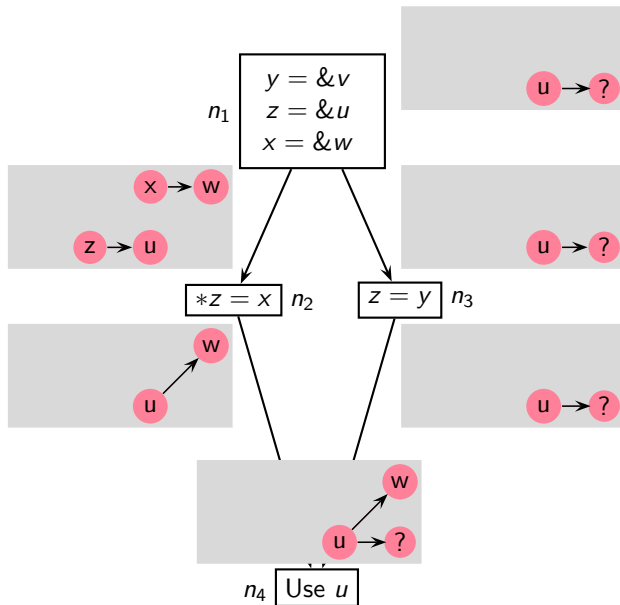
Is All This Information Useful?



Is All This Information Useful?



Is All This Information Useful?



Liveness-Based Ideal Points-to Analysis

- Let $(n, \sigma)_i \in \tau$, $i \geq 0$, denote the occurrence of program state (n, σ) at position i in trace τ
- The liveness-based restriction of τ , denoted $\text{Lv}(\tau)$, is computed by replacing $(n, \sigma)_i \in \tau$ by $(n, \sigma')_i$ where $\sigma' \subseteq \sigma$.

The state σ' is computed by retaining only those $((x, f) \mapsto a) \in \sigma$ for which (x, f) is read subsequently in τ before being defined

$$\left(\begin{aligned} &\exists j > i \text{ such that } (m, \cdot)_j \in \tau \wedge (x, f) \in \text{Ref}(m) \wedge \\ &(\nexists k, i < k < j \text{ such that } (l, \cdot)_k \in \tau \wedge (x, f) \in \text{Def}(l)) \end{aligned} \right)$$

- ▶ $\text{Def}(n)$ is same as the extractor function Def_n defined before (except that now we use a state σ along τ rather than the points-to information Ain_n)
- ▶ $\text{Ref}(n)$ will be defined shortly



Liveness-Based Ideal Points-to Analysis

- Liveness-Based Ideal May-Points-to analysis computes Points-to information reaching along the liveness-based restriction of all traces

$$RLS(n) = \{\sigma \mid (n, \sigma) \text{ occurs in some trace } Lv(\tau)\}$$

$$LvIdealMayPT(n) = \bigcup_{\sigma \in RLS(n)} \sigma$$

- It is easy to see that

$$\forall n \in N : LvIdealMayPT(n) \subseteq IdealMayPT(n)$$

- We redefine the soundness criterion in terms of $LvIdealMayPT$



The L and P of LFCPA

Mutual dependence of liveness and points-to information

- Define points-to information only for live pointers
- For pointer indirections, define liveness information using points-to information



The F and C of LFCPA

- Use call strings method for full flow and context sensitivity
- Use value contexts for efficient interprocedural analysis
[Khedker-Karkare-CC-2008, Padhye-Khedker-SOAP-2013]



Use of Strong Liveness

- Simple liveness considers every use of a variable as useful
- Strong liveness checks the liveness of the result before declaring the operands to be live



Use of Strong Liveness

- Simple liveness considers every use of a variable as useful
- Strong liveness checks the liveness of the result before declaring the operands to be live
- Strong liveness is more precise than simple liveness



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset		
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$		
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

- $Lin/Lout$: set of Live pointers, $Ain/Aout$: sets of mAy points-to pairs
- Ref_n , $Kill_n$, Def_n , and $Pointee_n$ are defined in terms of Ain_n



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointes_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset		
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$		
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

Pointers that become live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset		
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$		
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

Defined pointers must be live at the exit for the read pointers to become live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset		
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$		
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

Some pointers are unconditionally live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
<i>use x</i>	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$		
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

x is
unconditionally
live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$		
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

y is live
if defined pointers
are live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$		
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$	$\{y\} \cup A\{y\} \cap \mathbf{P}$	
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		

y and its
pointees in Ain_n are
live if defined pointers
are live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$	$\{y\} \cup A\{y\} \cap \mathbf{P}$	\emptyset
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$		
other	\emptyset	\emptyset	\emptyset		



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$	$\{y\} \cup A\{y\} \cap \mathbf{P}$	\emptyset
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$	$\{x, y\}$	
other	\emptyset	\emptyset	\emptyset		

y is live
if defined pointers
are live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$	$\{y\} \cup A\{y\} \cap \mathbf{P}$	\emptyset
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$	$\{x, y\}$	$\{x\}$
other	\emptyset	\emptyset	\emptyset		

x is
unconditionally
live



Extractor Functions for LFCPA

Unchanged from earlier points-to analysis

Generation of strong liveness

	Def_n	$Kill_n$	$Pointee_n$	Ref_n	
				$Def_n \cap Lout_n \neq \emptyset$	otherwise
$use\ x$	\emptyset	\emptyset	\emptyset	$\{x\}$	$\{x\}$
$x = \&a$	$\{x\}$	$\{x\}$	$\{a\}$	\emptyset	\emptyset
$x = y$	$\{x\}$	$\{x\}$	$A\{y\}$	$\{y\}$	\emptyset
$x = *y$	$\{x\}$	$\{x\}$	$A(A\{y\} \cap \mathbf{P})$	$\{y\} \cup A\{y\} \cap \mathbf{P}$	\emptyset
$*x = y$	$A\{x\} \cap \mathbf{P}$	$Must(A)\{x\} \cap \mathbf{P}$	$A\{y\}$	$\{x, y\}$	$\{x\}$
other	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset



Deriving *Must* Points-to for LFCPA

For $*x = y$, unless the pointees of x are known

- points-to propagation should be blocked
- liveness propagation should be blocked

to ensure monotonicity

$$Must(R) = \bigcup_{x \in \mathbf{P}} \{x\} \times \begin{cases} \bigvee & R\{x\} = \emptyset \vee R\{x\} = \{?\} \\ \{y\} & R\{x\} = \{y\} \wedge y \neq ? \\ \emptyset & \text{otherwise} \end{cases}$$



LFCPA Data Flow Equations

$$Lout_n = \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases}$$

$$Lin_n = (Lout_n - Kill_n) \cup Ref_n$$

$$Ain_n = \begin{cases} Lin_n \times \{?\} & n \text{ is } Start_p \\ \left(\bigcup_{p \in pred(n)} Aout_p \right) \Big|_{Lin_n} & \text{otherwise} \end{cases}$$

$$Aout_n = \left(\left(Ain_n - (Kill_n \times V) \right) \cup \left(Def_n \times Pointee_n \right) \right) \Big|_{Lout_n}$$

- *Lin/Lout*: set of Live pointers
- *Ain/Aout*: definitions remain unchanged except for restriction to liveness



LFCPA Data Flow Equations

$$\begin{aligned}
 Lout_n &= \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases} \\
 Lin_n &= (Lout_n - Kill_n) \cup Ref_n \\
 Ain_n &= \begin{cases} Lin_n \times \{?\} & n \text{ is } Start_p \\ \left(\bigcup_{p \in pred(n)} Aout_p \right) \Big|_{Lin_n} & \text{otherwise} \end{cases} \\
 Aout_n &= \left((Ain_n - (Kill_n \times V)) \cup (Def_n \times Pointee_n) \right) \Big|_{Lout_n}
 \end{aligned}$$

Kill_n defined in terms of *Ain_n*

- *Lin/Lout*: set of Live pointers
- *Ain/Aout*: definitions remain unchanged except for restriction to liveness



LFCPA Data Flow Equations

$$Lout_n = \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases}$$

$$Lin_n = (Lout_n - Kill_n) \cup Ref_n$$

Ref_n defined
in terms of Ain_n
and $Lout_n$

$$Ain_n = \begin{cases} Lin_n \times \{?\} & n \text{ is } Start_p \\ \left(\bigcup_{p \in pred(n)} Aout_p \right) \Big|_{Lin_n} & \text{otherwise} \end{cases}$$

$$Aout_n = \left(\left(Ain_n - (Kill_n \times V) \right) \cup \left(Def_n \times Pointee_n \right) \right) \Big|_{Lout_n}$$

- $Lin/Lout$: set of Live pointers
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LFCPA Data Flow Equations

$$Lout_n = \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases}$$

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$$Aout_n = \left(\left(Ain_n - (Kill_n \times V) \right) \cup \left(Def_n \times Pointee_n \right) \right) \Big|_{Lout_n}$$

Ain_n and $Aout_n$ are restricted to Lin_n and $Lout_n$

n is $Start_p$

- $Lin/Lout$: set of Live pointers
- $Ain/Aout$: definitions remain unchanged except for restriction to liveness



LFCPA Data Flow Equations

$$Lout_n = \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases}$$

$$Lin_n = (Lout_n - Kill_n) \cup Ref_n$$

$$Ain_n = \begin{cases} Lin_n \times \{?\} & n \text{ is } Start_p \\ \left(\bigcup_{p \in pred(n)} Aout_p \right) \Big|_{Lin_n} & \text{otherwise} \end{cases}$$

$$Aout_n = \left((Ain_n - (Kill_n \times V)) \cup (Def_n \times Pointee_n) \right) \Big|_{Lout_n}$$

BI
restricted to
live pointers

- *Lin/Lout*: set of Live pointers
- *Ain/Aout*: definitions remain unchanged except for restriction to liveness



LFCPA Data Flow Equations

$$Lout_n = \begin{cases} \emptyset & n \text{ is } End_p \\ \bigcup_{s \in succ(n)} Lin_s & \text{otherwise} \end{cases}$$

$$Lin_n = (Lout_n - Kill_n) \cup Ref_n$$

$$Ain_n = \begin{cases} Lin_n \times \{?\} & n \text{ is } Start_p \\ \left(\bigcup_{p \in pred(n)} Aout_p \right) \Big|_{Lin_n} & \text{otherwise} \end{cases}$$

$$Aout_n = \left(\left(Ain_n - (Kill_n \times V) \right) \cup \left(Def_n \times Pointee_n \right) \right) \Big|_{Lout_n}$$

- *Lin/Lout*: set of Live pointers
- *Ain/Aout*: definitions remain unchanged except for restriction to liveness

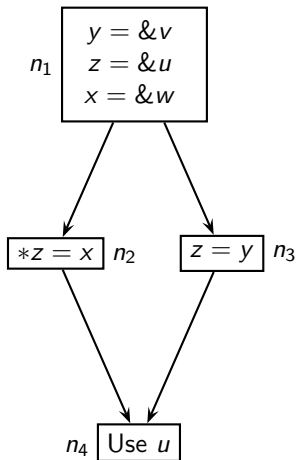


Motivating Example Revisited

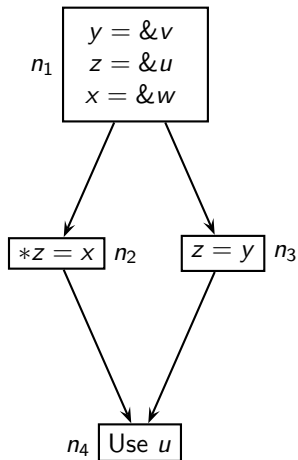
- For convenience, we show complete sweeps of liveness and points-to analysis repeatedly
- This is not required by the computation
- The data flow equations define a single fixed point computation



First Round of Liveness Analysis and Points-to Analysis



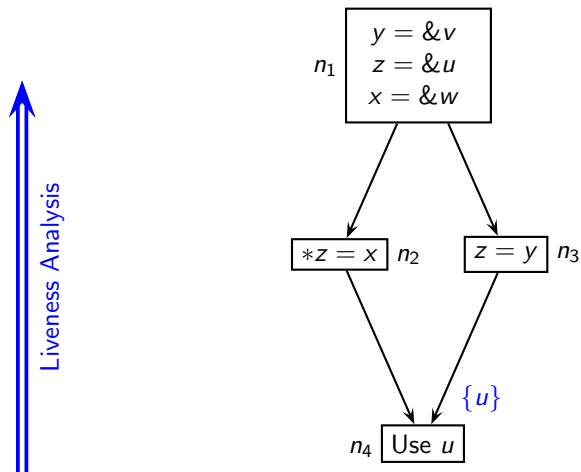
First Round of Liveness Analysis and Points-to Analysis



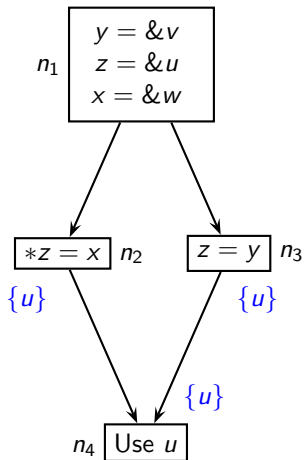
↑
Liveness Analysis



First Round of Liveness Analysis and Points-to Analysis



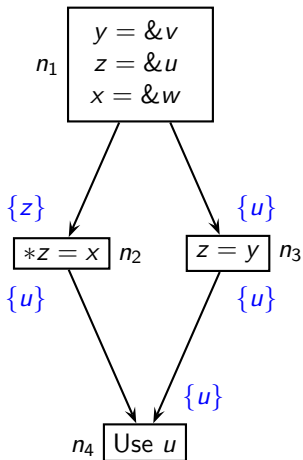
First Round of Liveness Analysis and Points-to Analysis



↑
Liveness Analysis



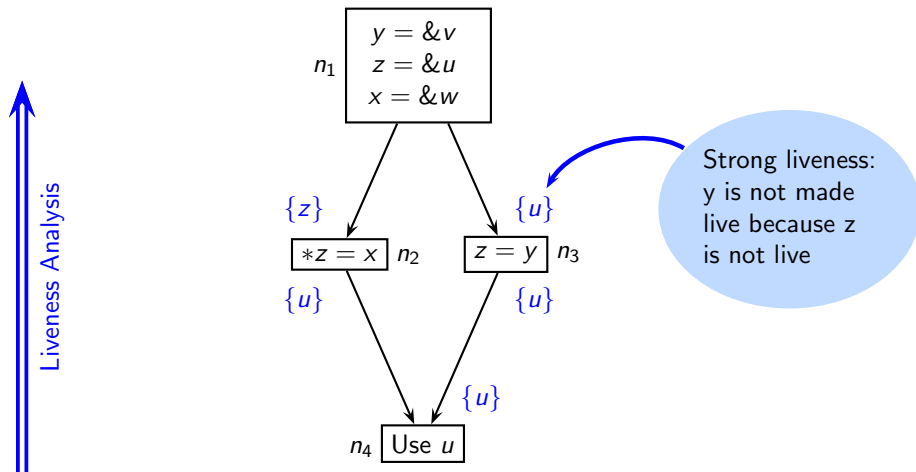
First Round of Liveness Analysis and Points-to Analysis



↑
Liveness Analysis

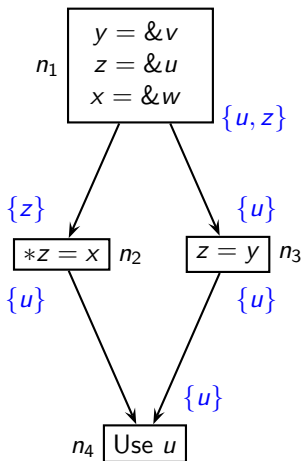


First Round of Liveness Analysis and Points-to Analysis

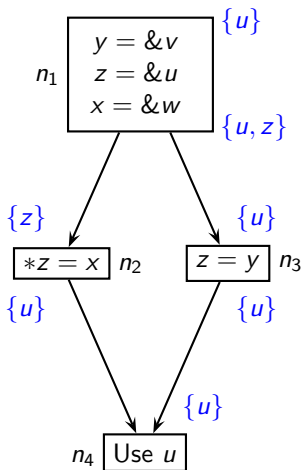


First Round of Liveness Analysis and Points-to Analysis

↑
Liveness Analysis



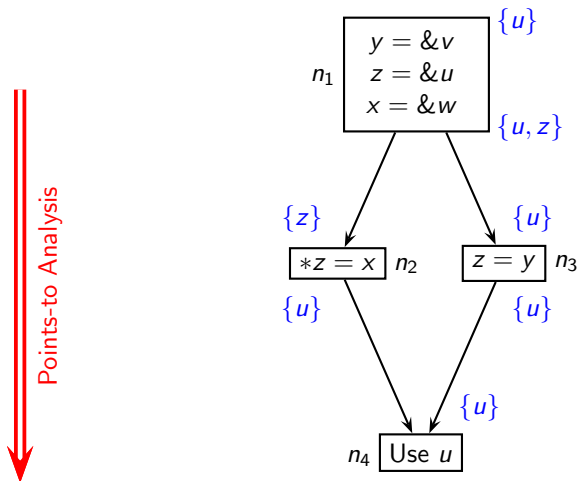
First Round of Liveness Analysis and Points-to Analysis



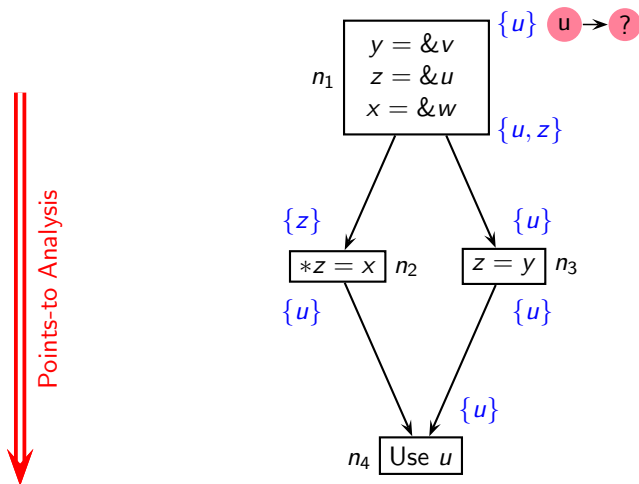
↑
Liveness Analysis



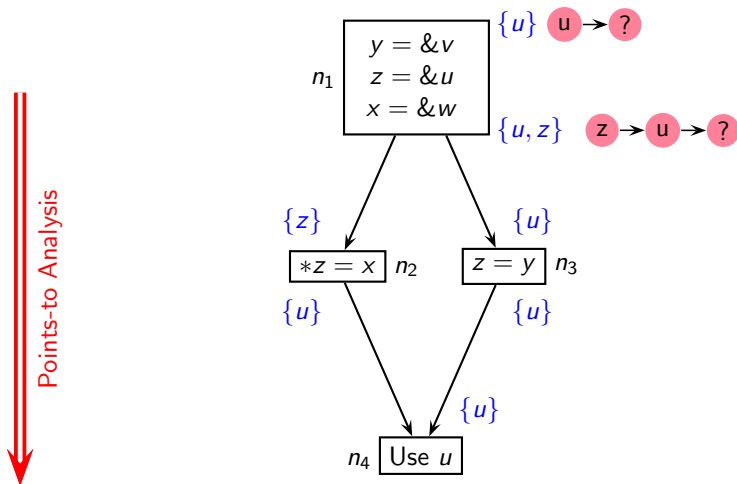
First Round of Liveness Analysis and Points-to Analysis



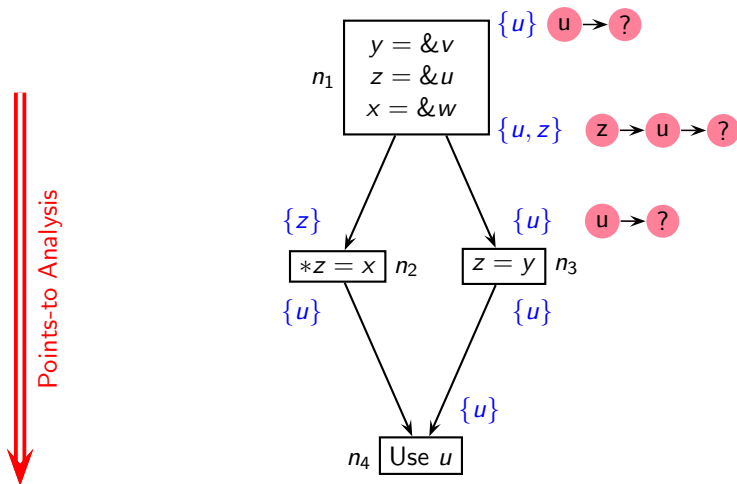
First Round of Liveness Analysis and Points-to Analysis



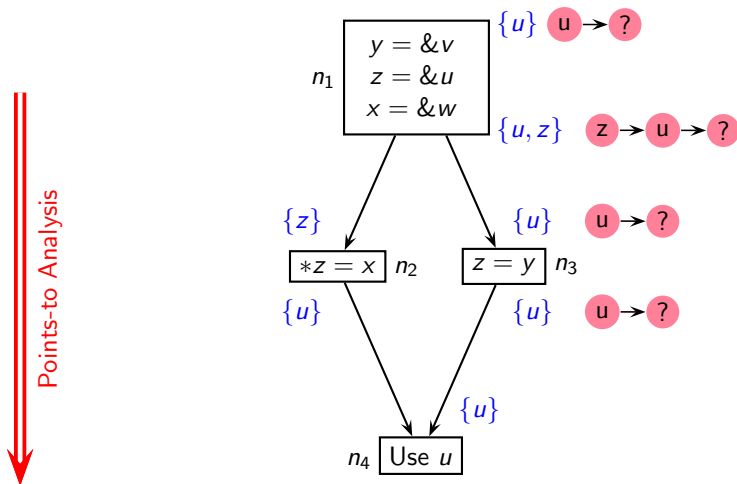
First Round of Liveness Analysis and Points-to Analysis



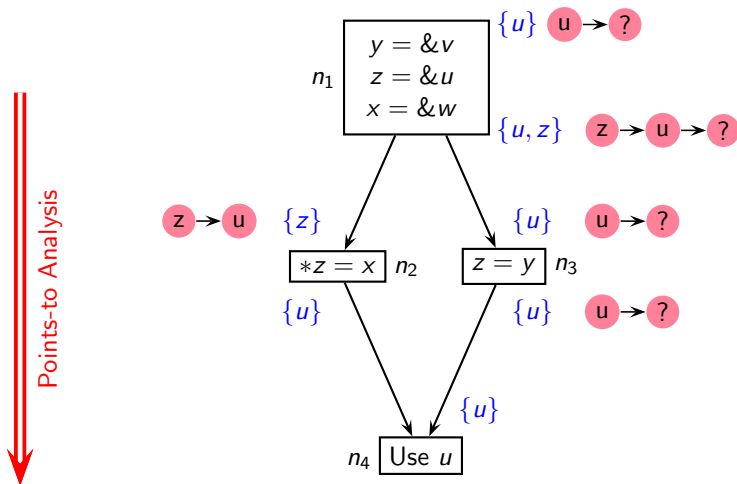
First Round of Liveness Analysis and Points-to Analysis



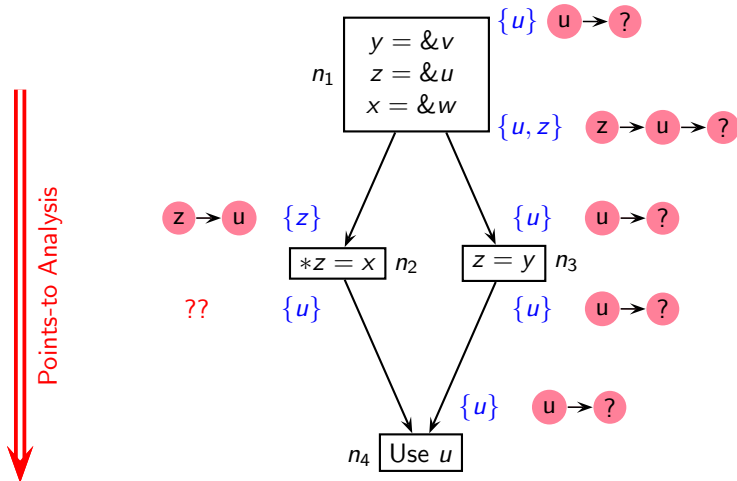
First Round of Liveness Analysis and Points-to Analysis



First Round of Liveness Analysis and Points-to Analysis

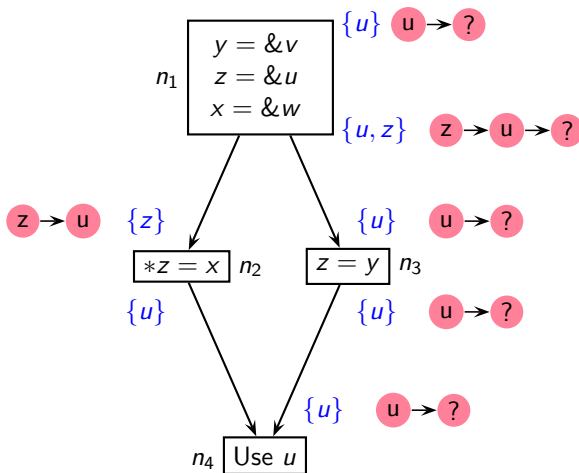


First Round of Liveness Analysis and Points-to Analysis



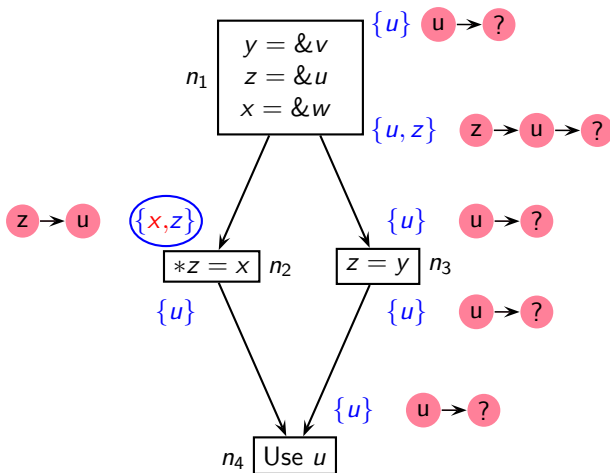
Second Round of Liveness Analysis and Points-to Analysis

↑
Liveness Analysis

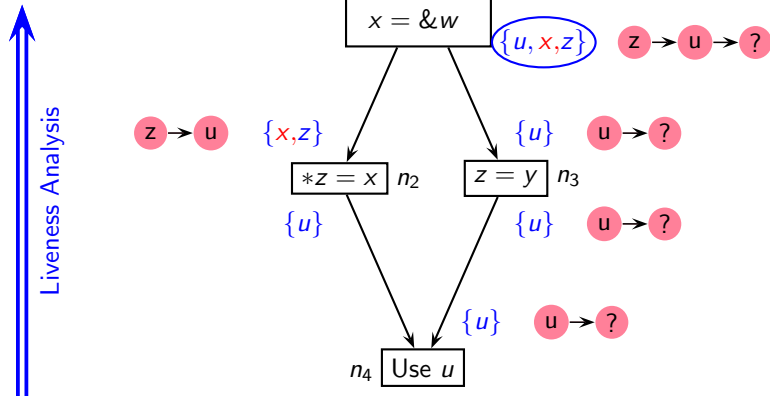


Second Round of Liveness Analysis and Points-to Analysis

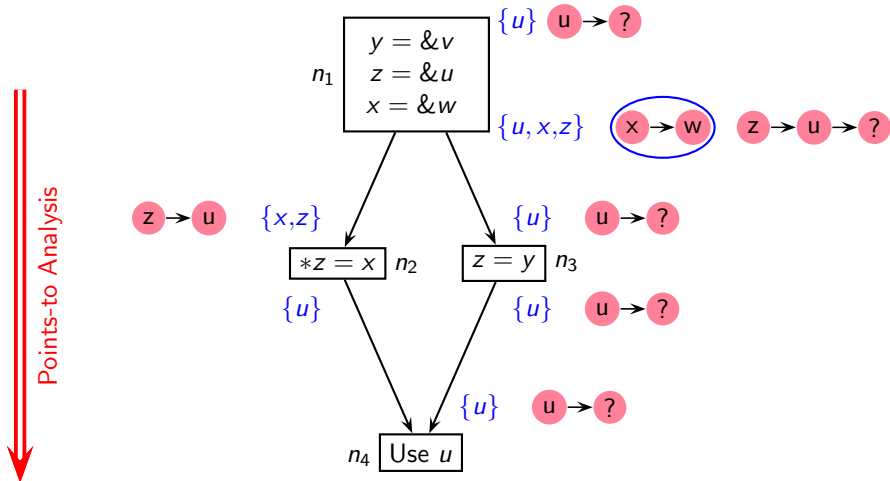
↑
Liveness Analysis



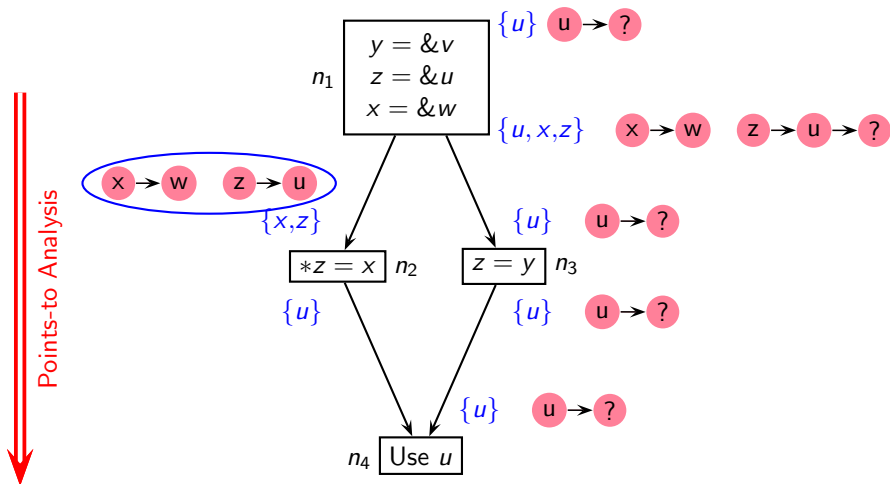
Second Round of Liveness Analysis and Points-to Analysis



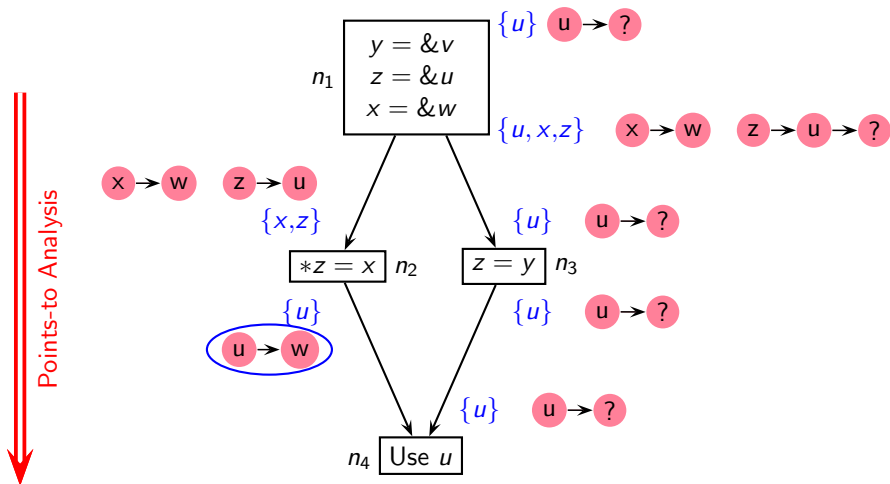
Second Round of Liveness Analysis and Points-to Analysis



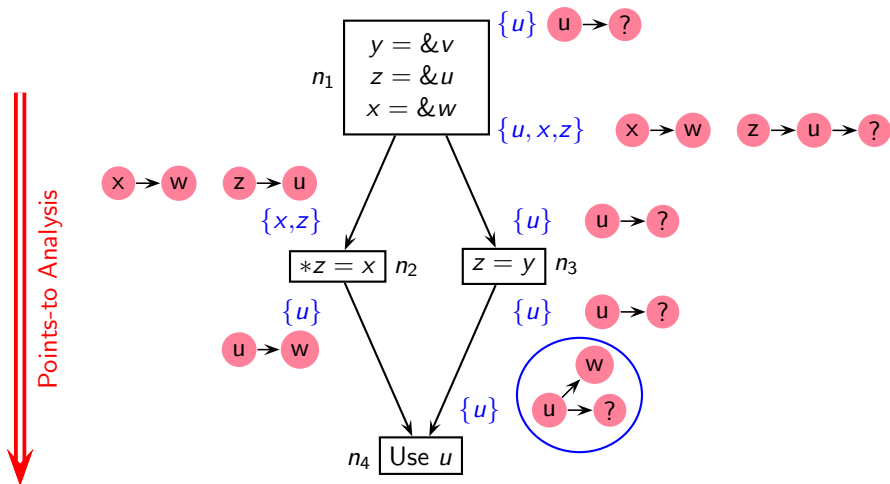
Second Round of Liveness Analysis and Points-to Analysis



Second Round of Liveness Analysis and Points-to Analysis



Second Round of Liveness Analysis and Points-to Analysis



LFCPA Observations

- Usable pointer information is very small and sparse
- Data flow propagation in real programs seems to involve only a small subset of all possible data flow values
- Earlier approaches reported inefficiency and non-scalability because they computed far more information than the actual usable information



LFCPA Lessons: The Larger Perspective

exhaustive
computation

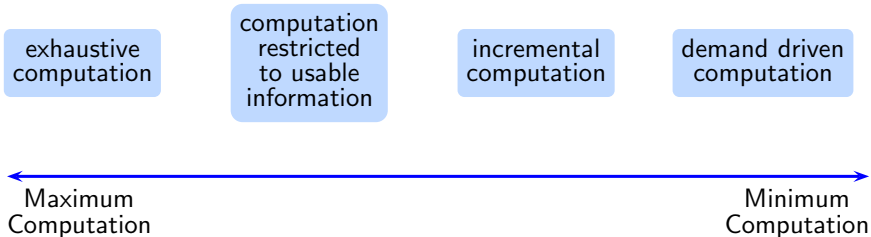
computation
restricted
to usable
information

incremental
computation

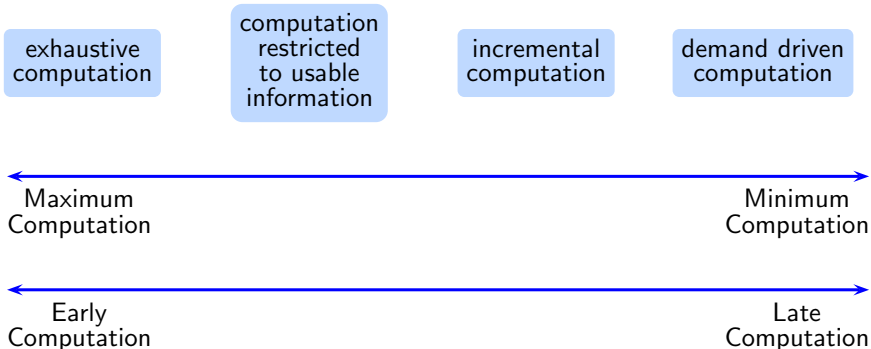
demand driven
computation



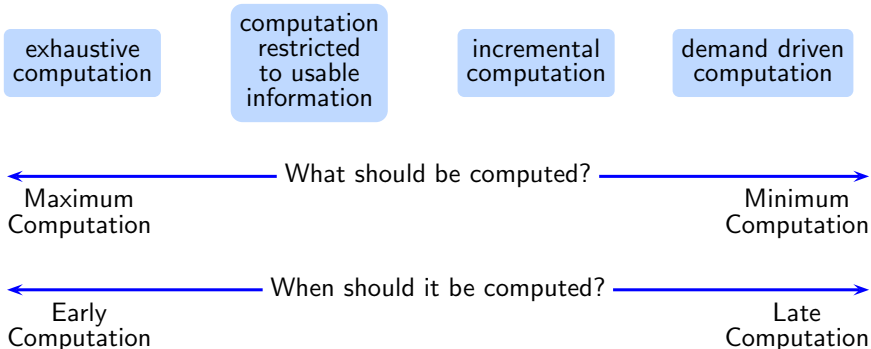
LFCPA Lessons: The Larger Perspective



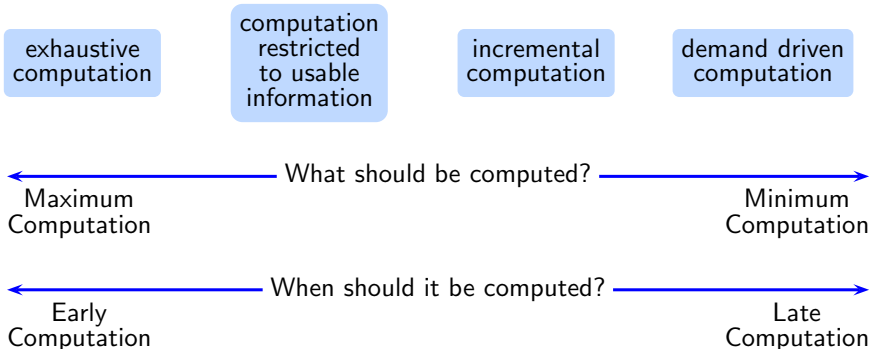
LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective

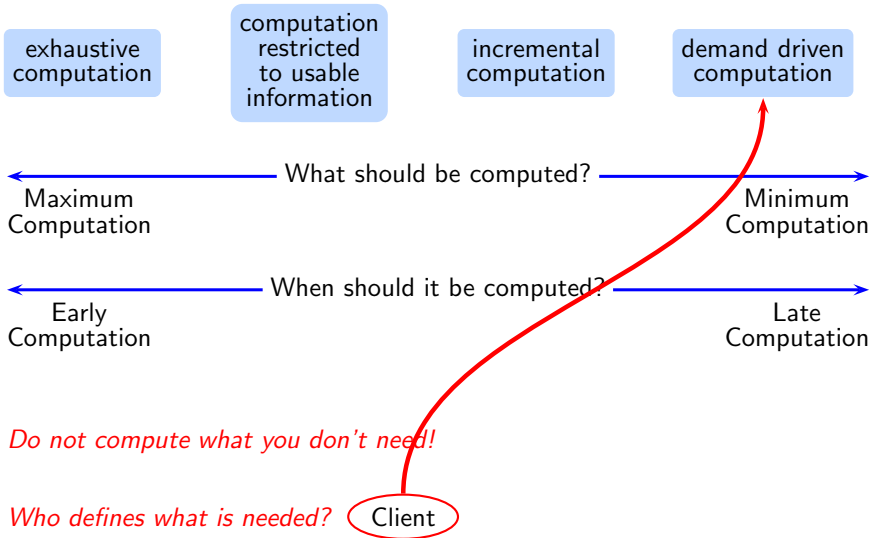


Do not compute what you don't need!

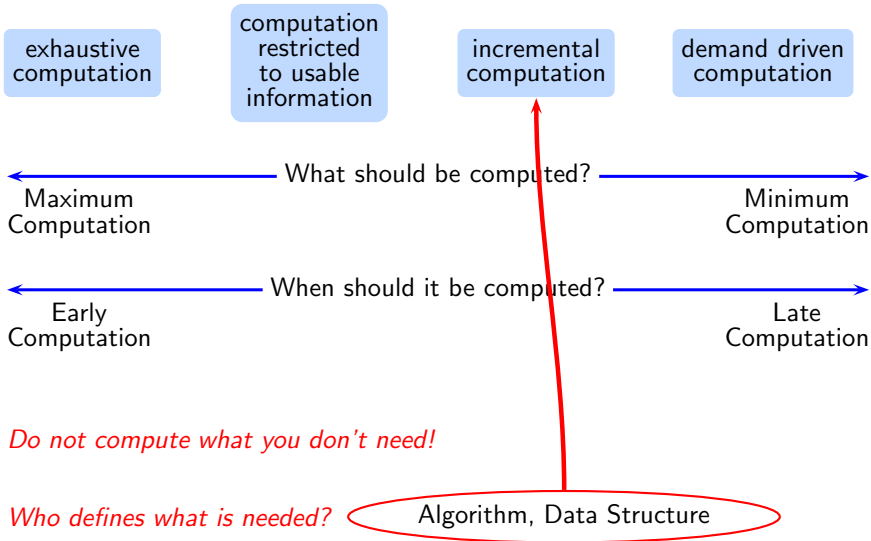
Who defines what is needed?



LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective

exhaustive
computation

computation
restricted
to usable
information

incremental
computation

demand driven
computation

← Maximum
Computation

← Early
Computation

Avoid computing some values because

- they have been computed before, or
- they can just be “adjusted”, or
- they are equivalent to some other values

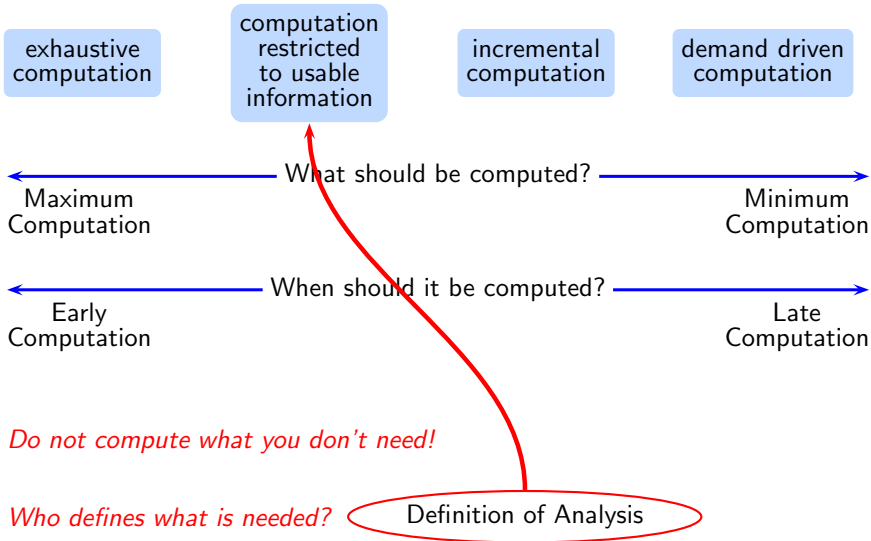
E.g. Value based termination of call strings,
Work list based methods, BDDs

Do not compute what you don't need!

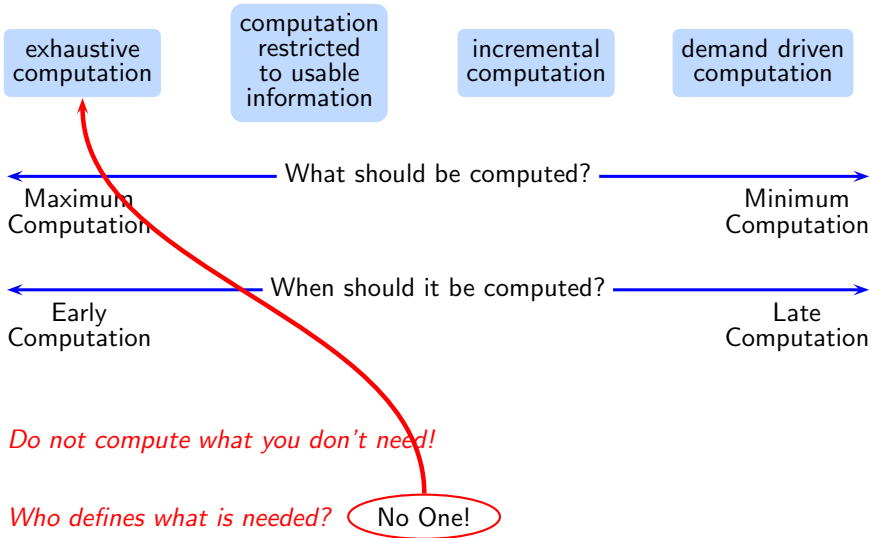
Who defines what is needed? Algorithm, Data Structure



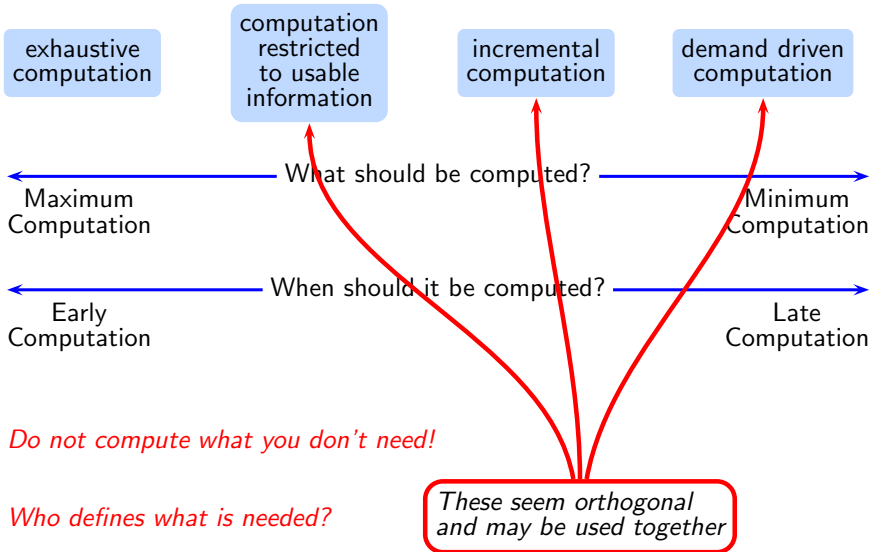
LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective



LFCPA Lessons: The Larger Perspective



An Outline of Pointer Analysis Coverage

- Pointer Statements
- Comparing Points-to and Alias information
- Defining Points-to Analysis
- Flow Insensitive Points-to Analysis
- Flow Sensitive Points-to Analysis
- Liveness Based Points-to Analysis
- Handling Heap Next Topic



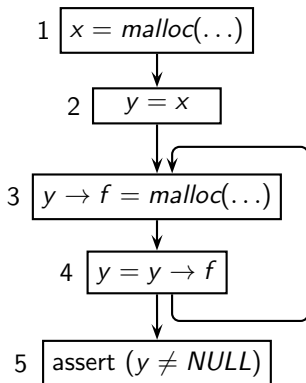
What About Heap Data?

- Compile time entities, abstract entities, or summarized entities
- Three options:
 - ▶ Represent all heap locations by a single abstract heap location
 - ▶ Represent all heap locations of a particular type by a single abstract heap location
 - ▶ Represent all heap locations allocated at a given memory allocation site by a single abstract heap location
- Summarization of pointer expression: Usually based on the length of pointer expression



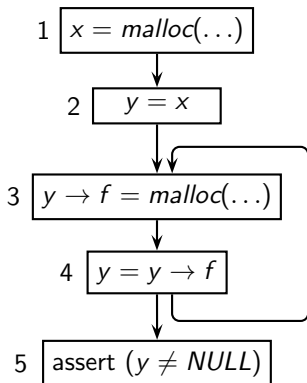
Allocation Site Based Abstraction of Points-to Graph

Program

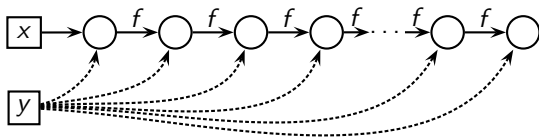


Allocation Site Based Abstraction of Points-to Graph

Program

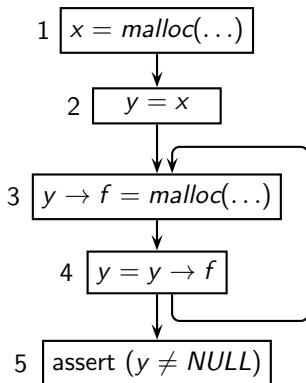


Memory graph representing multiple executions

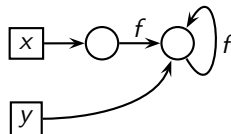
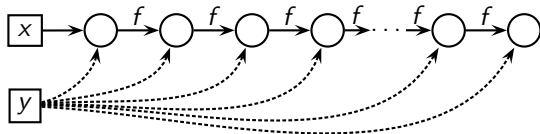


Allocation Site Based Abstraction of Points-to Graph

Program



Memory graph representing multiple executions

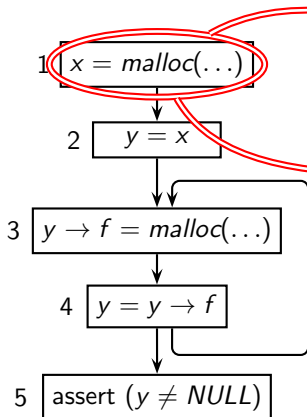


Allocation-site based
points-to graph

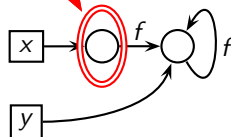
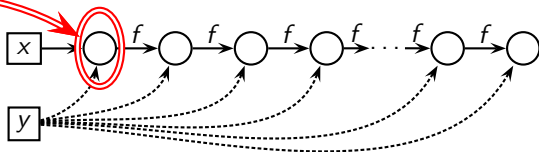


Allocation Site Based Abstraction of Points-to Graph

Program



Memory graph representing multiple executions

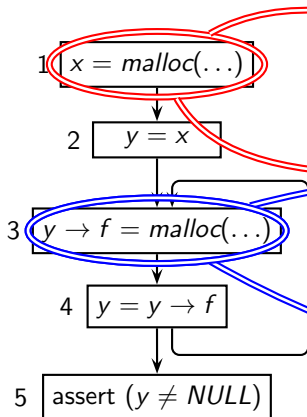


Allocation-site based points-to graph

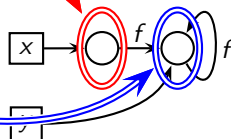
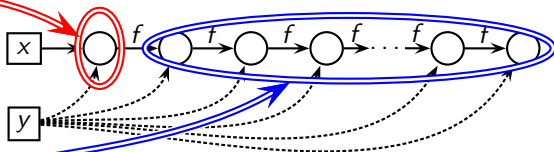


Allocation Site Based Abstraction of Points-to Graph

Program



Memory graph representing multiple executions



Allocation-site based
points-to graph

